R-GAGE® T30R Sensor

Instruction Manual

Original Instructions
217048 Rev. A
9 March 2021

217048

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1 Product Description

Radar-Based Sensors for Detection and Measurement of Moving and Stationary Targets

- FMCW radar detects moving and stationary objects
- Adjustable sensing field—ignores objects beyond setpoint
- Easy setup and configuration of range, sensitivity, and output using the Banner Radar Configuration Software
- Sensing functions are immune to wind, fog, steam, and temperature changes and resistant to rain and snow
- Compact, rugged IP67 housing withstands harsh environments

WARNING:

- **Do not use this device for personnel protection**
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or de-energized (off) output condition.

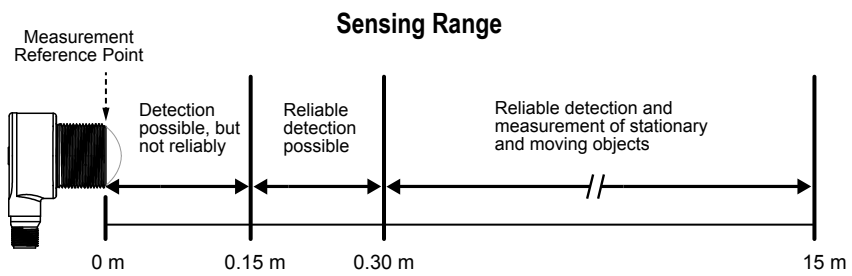
1.1 Models

Models [1]	Maximum Range	Connection	Supply Voltage	Telecom Approved	Output
T30R-1515-KIQ	15 m (49.2 ft)	Integral M12/Euro-style quick disconnect	10 V DC to 30 V DC	US, EU	Analog current (4 mA to 20 mA and 1 NPN/PNP discrete)
T30R-1515-KUQ			12 V DC to 30 V DC		Analog voltage (0 V to 10 V or 0.5 V to 4.5 V, and 1 NPN/PNP discrete)
T30R-1515-KDQ			10 V DC to 30 V DC		Dual discrete (NPN/PNP)

1.2 Overview

The T30R is an industrial radar sensor that uses high frequency radio waves from an internal antenna. It detects high-dielectric targets, such as metal or large amounts of water, and lower-dielectric materials, such as wood, rock, or organic material. The sensor can be configured with software, IO-Link, remote input wires, or push buttons to sense objects up to a specific distance, ignoring objects beyond this distance (background suppression). Or the sensor can be taught a reference point to detect the presence or absence of an objects (retroreflective).

Figure 1. Sensing Range



[1] Integral 5-pin M12/Euro-style quick disconnect models are listed. To order the 150 mm (6 in) PUR cable model with a M12/Euro-style quick disconnect, replace the suffix 'Q' with "QP" in the model number. For example, T30R-1515-KIQP.

1.3 Features and Indicators

Figure 2. T30R Features

	LED	Color	Description
1	Power	Green	Power ON
2	Signal Strength	Red	Flashes in proportion to the signal strength
3	Output 1	Amber	Target is within the taught analog span or discrete output status
4	Output 2	Amber	Discrete output status
5	NO/NC	Amber	Normally open/normally closed status of discrete output Dual discrete models have two LEDs
6	n/a	n/a	Output Teach buttons

Signal Strength and the Indicator LEDs

Signal Strength LED

Off: The signal strength less than one.

Flashing: The flashing is in proportion to the signal strength. The frequency increases as the signal strength increases from greater than 1× the user-selected signal strength threshold to 4× the signal strength threshold.

On: The signal strength is greater than 4× the user-selected signal strength threshold.

Output LEDs

Indicate that a target is present within the taught range and the signal strength is above the required signal strength threshold.

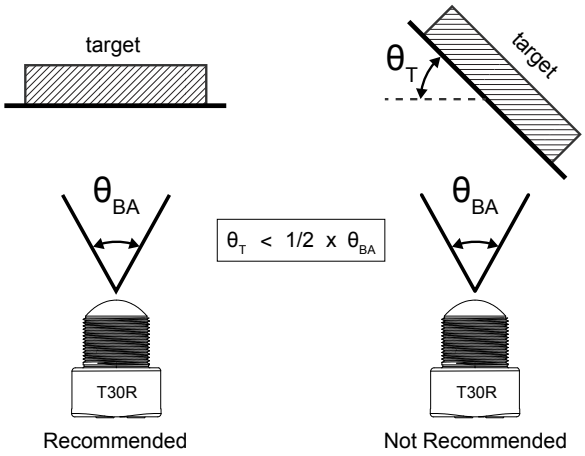
2 Installation Instructions

2.1 Sensor Orientation

Correct sensor-to-object orientation is important to ensure proper sensing.

Minimize the tilt angle of a target relative to the sensor. The target should be tilted less than half of the beam angle.

Figure 3. Tilt angle of the target relative to the sensor

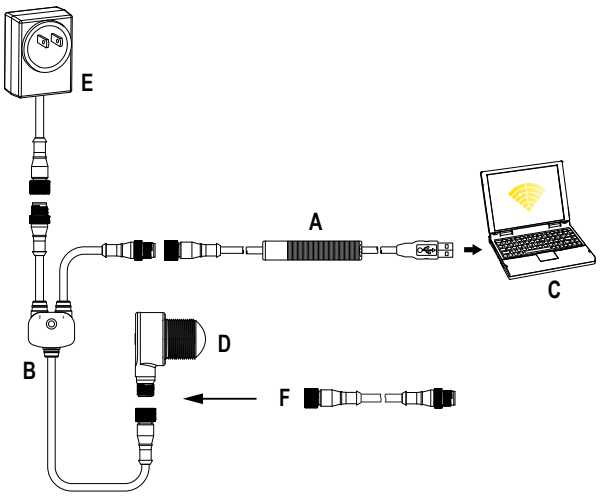


2.2 Mount the Device Using the Threaded Barrel

1. If your device came with a lock washer, place the lock washer on the barrel of the device.
2. Insert the barrel of the device though a hole or a bracket.
   - If desired and available, insert the device through an appropriately sized hole in the machine or equipment at the desired location.
   - If a bracket is needed, insert the device into the bracket.
3. Thread the mounting nut onto the barrel of the device, finger tight.
4. If using a bracket, mount the device and the bracket to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.
5. Check the device alignment, aiming it near parallel to, or down towards, the ground.

   If aiming at a target, alignment and signal strength can be checked via the red Signal Strength LED or the Banner Radar Configuration Software.
6. Tighten the nut.
7. If using a bracket, tighten the mounting screws to secure the device and the bracket in the aligned position.

2.3 Connect to the Sensor

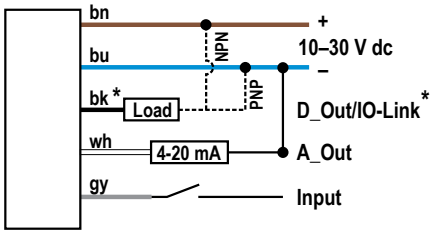


A = Pro Converter Cable (MQDC-506-USB)
B = Splitter (CSB-M1251FM1251M)
C = PC running Banner Radar Configuration software
D = T30R
E = Power Supply (PSW-24-1 or PSD-24-4)
F = Optional 5-Pin to 5-Pin Double-Ended Cordset (ex. MQDEC3-515SS)

2.4 Wiring

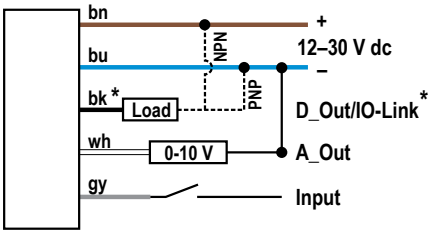
Quick disconnect wiring diagrams are functionally identical.

Push-pull Output and Analog Current Output



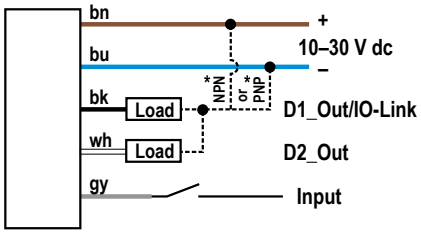
* Push-Pull output. User-configurable PNP/NPN setting.

Push-pull Output and Analog Voltage Output



* Push-Pull output. User-configurable PNP/NPN setting.

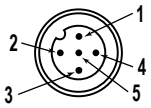
Dual Discrete Output



* Push-Pull output. User-configurable PNP/NPN setting.

Key:

1 = Brown
2 = White
3 = Blue
4 = Black
5 = Gray (Connect for use with remote input or Banner Radar Configuration software)



2.5 Install the Software

Important: Administrative rights are required to install the Banner Radar Configuration software.

1. Download the latest version of the software from www.bannerengineering.com/us/en/products/sensors/software/radar-configuration.html.
2. Navigate to and open the downloaded file.
3. Click **Install** to begin the installation process.
4. Depending on your system settings, a popup window may appear prompting to allow Banner Radar Configuration to make changes to your computer. Click **Yes**.
5. Click **Close** to exit the installer.

3 Getting Started

Power up the sensor, and verify that the power LED is ON green.

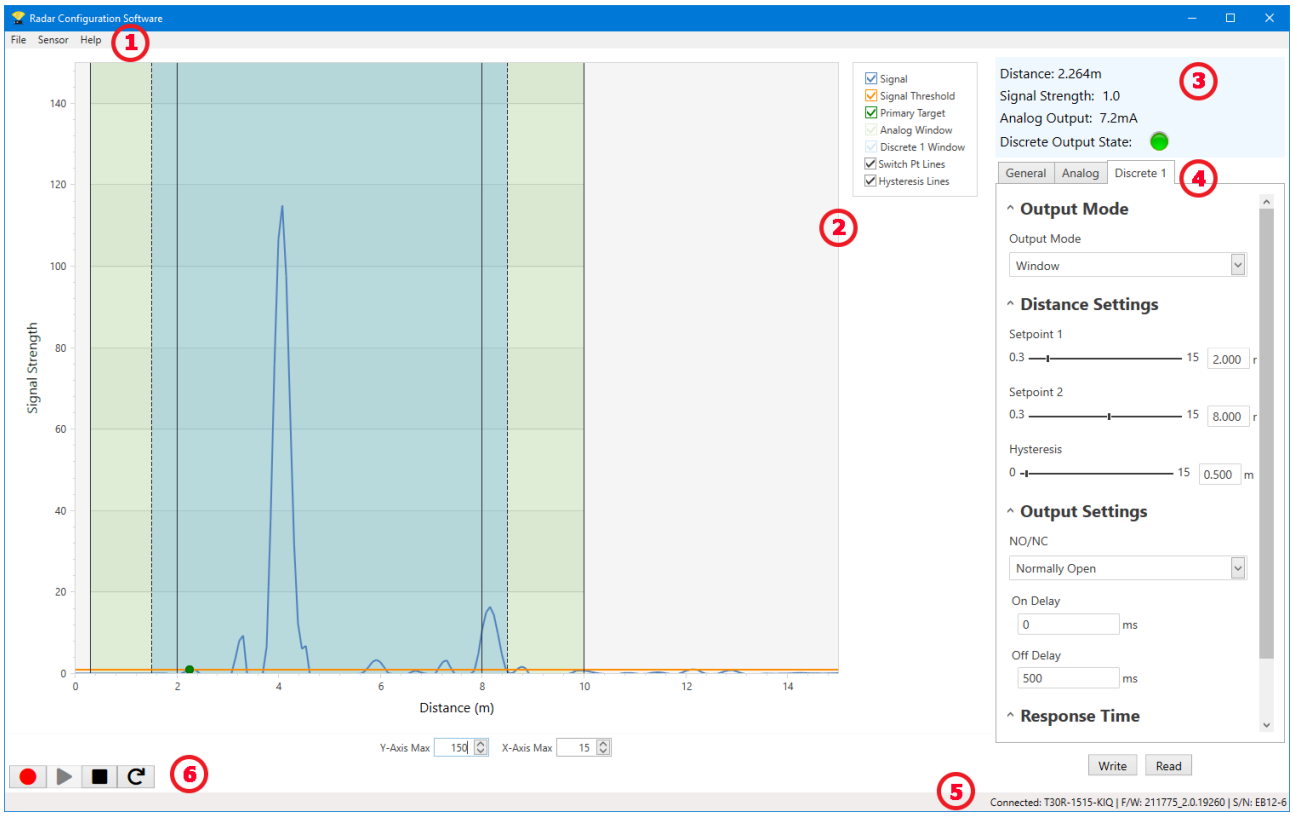
3.1 Connect to the Sensor

1. Connect the sensor to the splitter cable from the PRO-KIT. See Configuration Tool on p. 27.
2. Connect the external power and Pro Converter cable to the splitter cable.
3. Connect the Pro Converter cable to the PC.
4. Open the Banner Radar Configuration Software.
5. Go to **Sensor** > **Connect** on the **Navigation** toolbar.
   The **Connection** screen displays.
6. Select the correct **Sensor Model** and **Com Port** for the sensor.
7. Click **Connect**.
   The **Connection** screen closes and the sensor data displays.

3.2 Software Overview

Easy setup and configuration of range, sensitivity, and output using the Banner Radar Configuration and Pro Converter Cable.

Figure 4. Banner Radar Configuration Software



1. Navigation toolbar—Use this toolbar to connect to the sensor, to save or load a configuration, or to reset to factory defaults
2. Live Sensor Data and Legend—Shows the signal strength versus distance for the connected sensor, as well as options to select which data displays on the graph
3. Summary pane—Displays the distance to the target, the signal strength, and the output status
4. Sensor Settings pane—Set the sensor parameters in this pane
5. Status bar—Shows whether the sensor is connected, if a software update is available, and if the sensor data is being recorded to a file
6. Live Sensor Data controls—Use these controls to record, freeze, and play real-time sensor data, and to refresh the sensor connection

4 Banner Radar Configuration Workspace

4.1 Navigation Toolbar

Use this toolbar to connect to the sensor, to save or load a configuration, or to reset to factory defaults.

From the **File** menu, the following options are available:

Load Config
Load a configuration to the connected sensor. Use this option to set up multiple sensors with the same parameters.

Save Config
Save a configuration to a desired location for future use.

Reset Frequently Used Settings
Resets the software settings without changing the configuration of the attached sensor.

Exit
Exit the Banner Radar Configuration Software.

From the **Sensor** menu, the following options are available:

Connect
Connect to the sensor.

Disconnect
Disconnect from the sensor.

Factory Reset
Select to perform a factor reset on the sensor. All custom parameters will be lost.

From the **Help** menu, the following option is available:

About
Select to view the software version number, the copyright notice, and the warranty.

4.2 Live Sensor Data and Legend

The Live Sensor Data area displays the live distance and amplitude signal from the connected radar sensor. The signal strength threshold, switch point, and hysteresis are also plotted. Use these signals to evaluate targets to determine where the signal strength threshold and switch point should be configured for reliable detection.

Use the **Y-Axis Max** and the **X-Axis Max** to adjust the range displayed on the plot.

Legend

Use the legend to select which data appears on the graph.

Signal
Displays the strength of the signal over distance.

Signal Threshold
Displays the signal strength threshold.

Primary Targets
Represents the signal strength and location of the strongest target inside the switch point.

Analog Window [2]
The range the analog signal represents.
Available on analog models.

Discrete 1/2 Window [2]
The range for the discrete output.

Switch Pt Lines
Displays the switch point distance.

[2] Varies by output model.

Hysteresis Lines

Displays the hysteresis distance.

4.3 Summary Pane

The **Summary** pane (blue shaded area) displays **Distance**, **Signal Strength**, and **Output Status**.

Distance

Displays the distance to the target.

Signal Strength

Displays the amount of excess gain of the signal received from the target. The excess gain is relative to the minimum detection threshold (Signal Strength Threshold = 1).

Output Status

Displays whether the output is ON or OFF, or the analog output value (analog models only).

4.4 Sensor Settings Pane

Set parameters for the sensor.

Click **Read** to read the connected sensor's current parameters. Click **Write** to write the parameters to the sensor. Yellow highlight on a parameter's value indicates changes that have not yet been written to the sensor.

4.4.1 General Tab

The following are the parameters on the **General** tab on the **Sensor Settings** pane.

Response Speed

Choose the response speed of the sensor (Slow, Medium, Fast).

Target Selection

Signal Strength Threshold: Choose the threshold for the minimum amount of signal needed to actuate the output.

Target Mode:

Strongest Target—Output responds to the target with the highest signal strength that is over the signal strength threshold.

Nearest Target—Output responds to the nearest target that is over the signal strength threshold.

Advanced Target

Minimum Active Sensing Range: Sensor ignores anything from the face of the sensor to this defined range.

Maximum Active Sensing Range: Sensor ignores anything past this defined range.

Measurement Hold: A rate of change filter to smooth the output and reduce chatter. For more information, see Using Measurement Hold Example on p. 21.

Hold Time: The period of time that the sensor prevents the output from increasing or decreasing farther than the Maximum Distance Increase/Decrease. Available when **Measurement Hold** is set to enabled.

Maximum Distance Increase: The maximum amount that the **Measurement Hold** function allows the distance to increase, or move farther away from the sensor, in a given period of time called out by the **Hold Time**. Setting this to zero disables it. Available when **Measurement Hold** is set to enabled.

Maximum Distance Decrease: The maximum amount that the **Measurement Hold** function allows the distance to decrease, or move closer to the sensor, in a given period of time called out by the **Hold Time**. Setting this to zero disables it. Available when **Measurement Hold** is set to enabled.

Sensor Polarity

Define the output and remote input signal type.

Sensor Lockout

Remote Input (Gray Wire): Enable or disable the remote input wire.

Sensor Push Buttons: Enable or disable the push buttons.

4.4.2 Analog Tab

The following are the parameters on the **Analog** tab on the **Sensor Settings** pane. This tab is available for analog models.

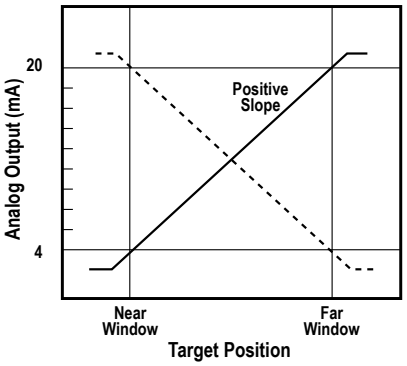
Analog Span

Define the outer limits of the analog range. This can be used to create a positive or negative slope.

Analog output options:

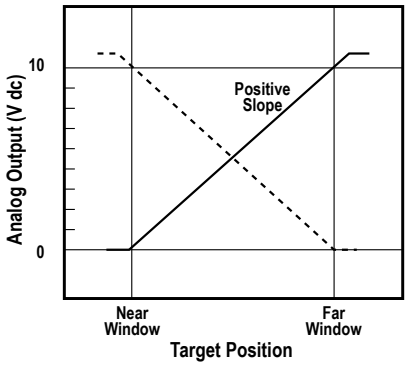
Current: 4 mA to 20 mA
Voltage: 0 V to 10 V or 0.5 V to 4.5 V

Figure 5. Slope—Current-Sourcing Models



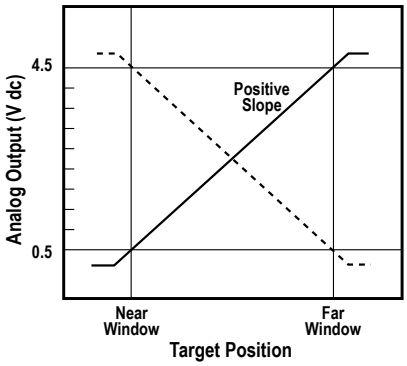
The analog current output tracks slightly beyond each window limit (from 3.8 mA to 20.2 mA)

Figure 6. Slope—Voltage-Sourcing Models, 0 V to 10 V



The analog current output tracks slightly beyond the upper window limit (up to 10.2 V)

Figure 7. Slope—Voltage-Sourcing Models, 0.5 V to 4.5 V



The analog current output tracks slightly beyond each window limit (0V - 5V)

Output

Loss–of–Signal: Sets the Analog Output value used by the sensor during a loss of signal. When a signal is restored, measurement resumes.

Hold Last Value—The Analog Output holds the last value indefinitely during a loss of signal.
3.5 mA (0 V)—The Analog Output switches to this value 2 seconds after a loss of signal. For Voltage models, this is 0 V. (Default)
20.5 mA (10.5 V/5 V)—The Analog Output switches to this value 2 seconds after a loss of signal. For Voltage models, this is 10.5 V.

Averaging: Use this menu to set the number of measurements that are averaged together for the analog output. Increasing the averaging improves repeatability but increases the total response speed. The default is 1. The filter can be set to 1, 2, 4, 8, 16, 32, 64, or 128. The total response time is show under Response Time.

Response Time

Calculates the total response time, taking into account the general response speed and averaging.

Table 1: Analog

Response Speed	Analog Output Filter Setting							
	1	2	4	8	16	32	64	128
	Analog Output Spec (ms)							
Fast	2	4	8	16	32	64	128	256
Medium	20	40	80	160	320	640	1280	2560
Slow	100	200	400	800	1600	3200	6400	12500

4.4.3 Discrete 1 Tab

The following are the parameters on the **Discrete 1** tab on the **Sensor Settings** pane.

Output Mode

Select **Switch Point** or **Window**.

Switch Point: The distance at which the switch point threshold is placed.

Window: Define two set points to create window limits.

Distance Settings

Define the set point(s) and the hysteresis.

Output Settings

NO/NC: Select **Normally Open** or **Normally Closed** from the list.

On Delay: Set an on delay in milliseconds. The maximum time is 60,000 ms.

Off Delay: Set an off delay in milliseconds. The maximum time is 60,000 ms.

Response Time

Calculates the total response time, taking into account the general response speed and on or off delays.

Table 2: Discrete

Response Speed	Discrete Output ON Spec (ms)	Discrete Output OFF Spec (ms)
Fast	6	6
Medium	50	100
Slow	200	500

4.4.4 Discrete 2 Tab

The following are the parameters on the **Discrete 2** tab on the **Sensor Settings** pane. This tab is available for dual discrete models.

Output Mode

Select **Switch Point**, **Window**, **Complementary**, or **Pulse Pro/PFM**.

Switch Point: Set a single switch point for the output to change.

Window: Define two setpoints to create window limits.

Complementary: Output 2 will be opposite of Output 1.

Pulse Pro/PFM: Pulse Pro/PFM output to interface with Banner lights or a PLC with PFM inputs.

Distance Settings

Available when Output Mode is set to **Switch Point** or **Window**.

Define the set point(s) and the hysteresis.

Output Settings

Available when Output Mode is set to **Switch Point** or **Window**.

NO/NC: Select **Normally Open** or **Normally Closed** from the list.

On Delay: Set an on delay in milliseconds. The maximum time is 60,000 ms.

Off Delay: Set an off delay in milliseconds. The maximum time is 60,000 ms.

Response Time

Calculates the total response time, taking into account the general response speed and on or off delays.

Table 3: Discrete

Response Speed	Discrete Output ON Spec (ms)	Discrete Output OFF Spec (ms)
Fast	6	6
Medium	50	100
Slow	200	500

Pulse Pro/PFM Settings

Available when Output Mode is set to **Pulse Pro/PFM**.

The T30R can generate pulses whose frequency are proportional to the sensor's measured distance, thereby providing a method for representing an analog signal with only a discrete counter. The sensing range of the sensor is scaled from 100 Hz to 600 Hz. 100 Hz equals the near range limit of the sensor, and 600 Hz equals the far sensing range limit. An output of 50 Hz or 650 Hz (user defined in the software) represents a loss of signal condition where there is no target or the target is out of range. This output can be tied directly to a number of Banner lights for visual feedback without the need for a controller.

100 Hz: Define the near sensing range limit of the Pulse Pro range.

600 Hz: Define the far sensing range limit of the Pulse Pro range.

Loss–of–Signal: Sets the value used by the sensor during a loss of signal. When a signal is restored, measurement resumes.

Hold last value—The Discrete 2 Output holds the last value indefinitely during a loss of signal.

50 Hz—The Discrete 2 Output switches to this value 2 seconds after a loss of signal.

650 Hz—The Discrete 2 Output switches to this value 2 seconds after a loss of signal.

4.5 Live Sensor Data Controls

After connecting to the sensor, data sampling begins automatically (but not recording).

To stop data sampling, click ■ **Stop**.

To restart data sampling, click ▶ **Play**. This only samples data from the sensor and displays it on the plot; it does not record the data to a log file.

To record data to a log file, click ● **Record**. The log file selection prompt displays. Save the log file as desired. The log file format is .csv.

If communication to the sensor is lost, click ↻ **Refresh Device Connection** to reconnect.

5 Configuring a Sensor

5.1 Banner Radar Configuration Software

Use the Banner Radar Configuration software and PRO-KIT to set up the R-GAGE sensor.

For more information visit www.bannerengineering.com/us/en/products/sensors/software/radar-configuration.html.

5.2 IO-Link Interface

IO-Link is a point-to-point communication link between a master device and sensor. Use IO-Link to parameterize sensors and transmit process data automatically.

For the latest IO-Link protocol and specifications, see www.io-link.com.

Each IO-Link device has an IODD (IO Device Description) file that contains information about the manufacturer, article number, functionality etc. This information can be easily read and processed by the user. Each device can be unambiguously identified via the IODD as well as via an internal device ID. Download the T30R's IO-Link IODD package (p/n 216168 for analog models and p/n 217271 for dual discrete models) from Banner Engineering's website at www.bannerengineering.com.

Banner has also developed Add On Instruction (AOI) files to simplify ease-of-use between the T30R, multiple third-party vendors' IO-Link masters, and the Logix Designer software package for Rockwell Automation PLCs. Three types of AOI files for Rockwell Allen-Bradley PLCs are listed below. These files and more information can be found at www.bannerengineering.com.

Process Data AOIs—These files can be used alone, without the need for any other IO-Link AOIs. The job of a Process Data AOI is to intelligently parse out the Process Data word(s) in separate pieces of information. All that is required to make use of this AOI is an EtherNet/IP connection to the IO-Link Master and knowledge of where the Process Data registers are located for each port.

Parameter Data AOIs—These files require the use of an associated IO-Link Master AOI. The job of a Parameter Data AOI, when working in conjunction with the IO-Link Master AOI, is to provide quasi-realtime read/write access to all IO-Link parameter data in the sensor. Each Parameter Data AOI is specific to a given sensor or device.

IO-Link Master AOIs—These files require the use of one or more associated Parameter Data AOIs. The job of an IO-Link Master AOI is to translate the desired IO-Link read/write requests, made by the Parameter Data AOI, into the format a specific IO-Link Master requires. Each IO-Link Master AOI is customized for a given brand of IO-Link Master.

Add and configure the relevant Banner IO-Link Master AOI in your ladder logic program first; then add and configure Banner IO-Link Device AOIs as desired, linking them to the Master AOI as shown in the relevant AOI documentation.

5.3 Push Button Configuration

Using the push buttons, the first and second points can be taught. If other changes to the configuration are needed, use either the Banner Radar Configuration Software or the remote input.

Figure 8. Analog Teach

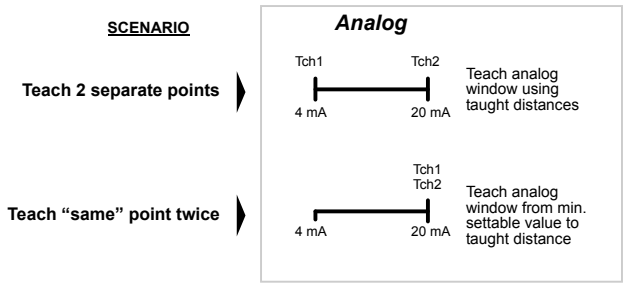
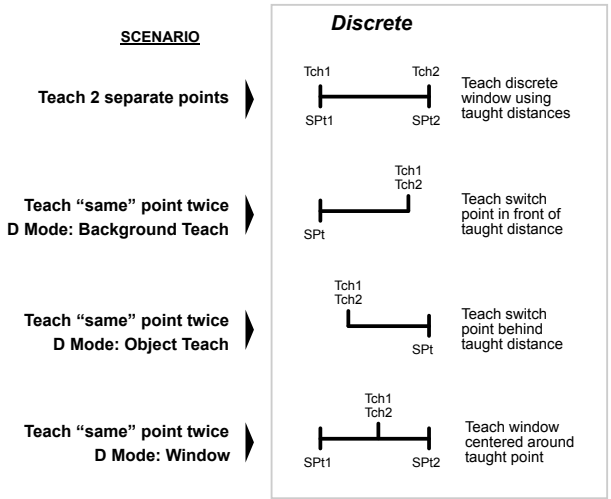


Figure 9. Discrete Teach



Note: Teach modes must be set with the remote input wire.

To cancel a configuration while in process, press and hold the button for the output being taught for longer than 2 seconds.

1. To enter TEACH mode, press and hold the button for the desired output.

   The buttons are **Analog** and **Discrete** (analog models) and **Discrete 1** and **Discrete 2** (discrete models).

   The green Power LED turns OFF, the yellow LED of the output being taught turns ON, and the yellow LED of the output not being taught turns OFF.
2. Position the target.
3. Press the button for the desired output one time to configure the first point.
   The yellow LED of the output being taught flashes.
4. Position the target.
5. Press the button for the desired output one time to configure the second point.
   The green Power LED turns on.

5.4 Remote Input

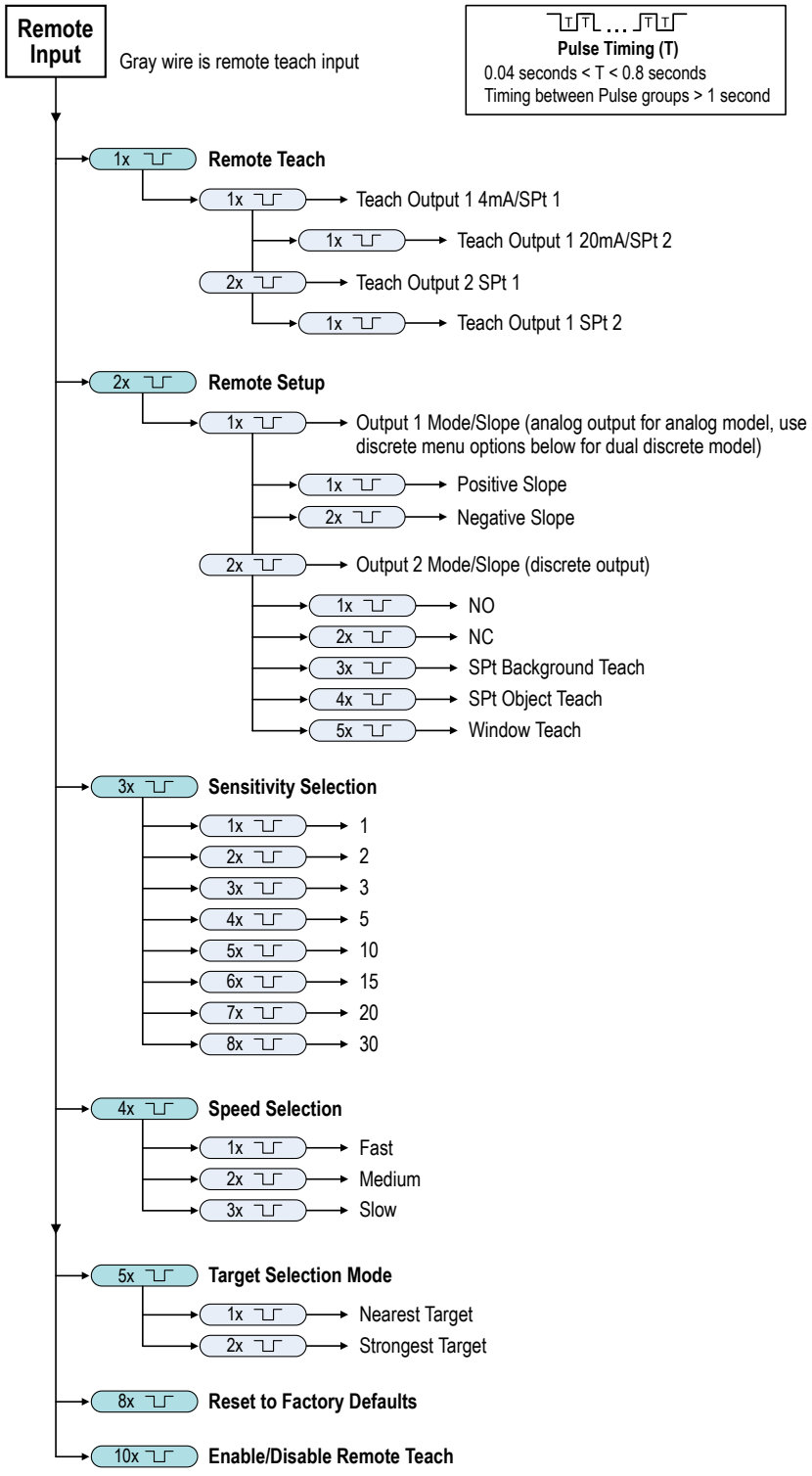
Use the remote input to program the sensor remotely.

The remote input provides limited programming options and is Active Low, but can be configured in the software. For active low, connect the gray input wire to ground (0 V dc), with a remote switch connected between the wire and ground. Remote teach can also be performed using the button on the Pro Converter Cable. The remote input wire is disabled by default. Pulse the remote input wire 10 times or use the Banner Radar Configuration Software to enable the feature. After enabling the remote input feature, pulse the remote input according to the diagram and the instructions provided in this manual.

The length of the individual programming pulses is equal to the value T: **0.04 seconds ≤ T ≤ 0.8 seconds**.

Exit remote programming modes by setting the remote input Low for longer than 2 seconds or by waiting for 60 seconds.

Figure 10. Remote Input Map



Note: If a factory reset is performed through the Banner Radar Configuration Software, the remote input wire becomes disabled (factory default setting). If the sensor is returned to factory defaults by using the remote input wire, the input wire remains enabled and the rest of the settings are restored to factory defaults.

5.4.1 Remote Teach

Use the following procedure to teach the first and second switch points.

1. Pulse the remote input once.

   The green Power LED flashes, the yellow LED is off, and the red LED is off.
2. Present the first point.
3. Teach the switch point.

Action	Result
Single-pulse the remote input. 	**Teach Accepted** The green Power LED is off, the yellow LED of the output being taught flashes while the yellow LED of the output not being taught is off. The red LED indicates signal strength. **Teach Not Accepted** The green Power LED continues to flash, the yellow LED is off, and the red LED is off. Retry teaching the first point.

4. Present the second point.
5. Teach the switch point.

Action	Result
Single-pulse the remote input. 	The green Power LED turns on. **Teach Accepted** The sensor returns to run mode. **Teach Not Accepted** The green Power LED remains off, the yellow LED of the output being taught continues to flash while the yellow LED of the output not being taught is off. Retry teaching the second point.

5.4.2 Remote Setup

Use Remote Setup to set the output mode to set normally open or normally closed, change the analog slope, or set the teach mode.

While in remote set up, pulsing the remote wire once configures output 1. For analog models, the slope of the output changes. For discrete output, output 1 and output 2 options are identical.

Changing the Output Mode using remote input affects both the output configuration (normally open versus normally closed) and the Teach mode. The output configuration change takes effect immediately and can be used to change the output between normally open and normally closed or the analog slope without changing the switch point distance. The change in Teach mode does not immediately change the switch point location, but will affect the behavior of the next remote Teach.

Analog Teach Modes

The default is to teach two separate points. With a positive slope, the first taught point is 4 mA and the second taught point is 20 mA.

If the two taught points are within 100 mm or less, the sensor views them as the same point. It considers that point as the 20 mA spot and sets the 4 mA spot at 300 mm. If a taught point is within the dead zone, the sensor sets that point at 300 mm.

Discrete Teach Modes

Teaching two separate points creates a window around that range.

Background Teach—Teaching the same point twice (points within 100 mm of each other) sets the switch point 200 mm in front of the taught point.

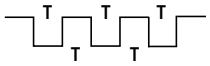
Object Teach—Teaching the same point twice (points within 100 mm of each other) sets the switch point 100 mm behind the taught point.

Window Teach—Teaching the same point twice (points within 100 mm of each other) sets a window ±50 mm on either side of the taught point, for a total window size of 100 mm.

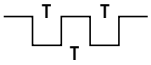
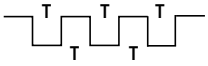
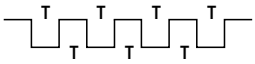
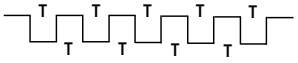
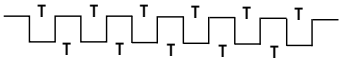
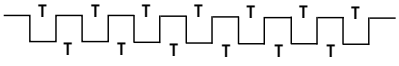
Set the Sensitivity

Use Sensitivity Selection to set the signal strength threshold.

1. Access Sensitivity Selection.

Action	Result
Triple-pulse the remote input. 	The green power LED flashes slowly.

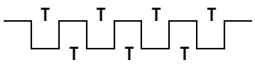
2. Select the desired signal threshold.

Action		Result
Pulses	**TEACH Mode**	The signal threshold is set and the green power LED flashes equal to the number of pluses, pauses, and then flashes equal to the number of pulses a second time. Then the sensor exits remote teach and returns to run mode.
1 	Signal Strength Threshold = 1	
2 	Signal Strength Threshold = 2	
3 	Signal Strength Threshold = 3	
4 	Signal Strength Threshold = 5	
5 	Signal Strength Threshold = 10	
6 	Signal Strength Threshold = 15	
7 	Signal Strength Threshold = 20	
8 	Signal Strength Threshold = 30	

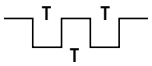
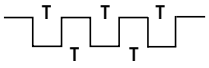
Set the Speed

Use Speed Selection to set the speed of the sensor.

1. Access Speed Selection.

Action	Result
Four-pulse the remote input. 	The green power LED flashes slowly.

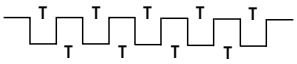
2. Select the desired signal threshold.

Action		Result
Pulses	**TEACH Mode**	The speed is set and the power LED flashes equal to the number of pluses, pauses, and then flashes equal to the number of pulses a second time. The sensor exits remote teach and returns to run mode.
1 	Speed = Fast	
2 	Speed = Medium	
3 	Speed = Slow	

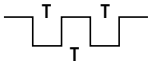
Target Selection Mode

Use Target Selection to set the target that the output sees.

1. Access Target Selection mode.

Action	Result
Five-pulse the remote input. 	The green power LED flashes slowly.

2. Select the desired signal threshold.

Action		Result
Pulses	**TEACH Mode**	The signal threshold is set and the green power LED flashes equal to the number of pluses, pauses, and then flashes equal to the number of pulses a second time. Then the sensor exits remote teach and returns to run mode
1 	Nearest Target—Output responds to the nearest target that is over the signal strength threshold.	
2 	Strongest Target—Output responds to the target with the highest signal strength that is over the signal strength threshold.	

5.5 Reset the Sensor to Factory Defaults

Reset the sensor to factory default settings using one of two methods.

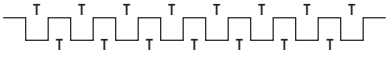
Note: If a factory reset is performed through the Banner Radar Configuration Software, the remote input wire becomes disabled (factory default setting). If the sensor is returned to factory defaults by using the remote input wire, the input wire remains enabled and the rest of the settings are restored to factory defaults.

Reset Using the Banner Radar Configuration Software

Go to **Sensor** > **Factory Reset**. The sensor indicators flash once, the sensor is reset back to the factory default settings, and a confirmation message displays.

Reset Using the Remote Input

Eight-pulse the remote input to apply the factory defaults.



5.5.1 Factory Default Settings

Table 4: General Tab Default Settings

Setting	Factory Default
Response Speed	Medium
Signal Strength Threshold	1.0
Target Mode	Nearest Target
Measurement Hold	Disabled
Discrete Output & Remote Input	PNP
Remote Input Wire	Disabled
Push Buttons	Enabled

Table 5: Analog Tab Default Settings

Setting	Factory Default
Range	4 mA to 20 mA (0 V to 10 V)
4mA/0V Point	0.3 m (1 ft)
20mA/10V Point	15.0 m (49.2 ft)
Loss of Signal	3.5 mA (0 V)
Averaging	1× (no averaging)

Table 6: Discrete 1 Tab Default Settings

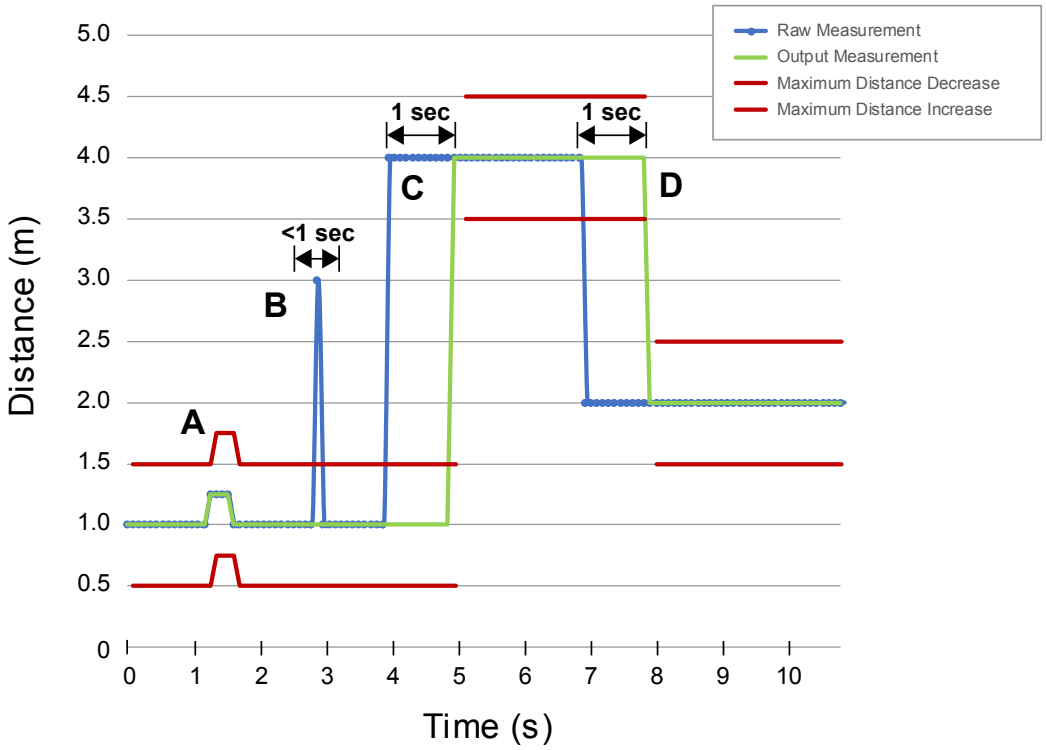
Setting	Factory Default
Output Mode	Switch Point
Setpoint 1	15.0 m (49.2 ft)
Hysteresis	0.05 m (2 in)
NO/NC	Normally Open
On Delay	0 ms
Off Delay	500 ms

Table 7: Discrete 2 Tab Default Settings

Setting	Factory Default
Output Mode	Switch Point
Setpoint 1	15.0 m (49.2 ft)
Hysteresis	0.05 m (2 in)
NO/NC	Normally Open
On Delay	0 ms
Off Delay	500 ms

5.6 Using Measurement Hold Example

Figure 11. Measurement Hold



The Hold Time is set to 1 second.

A. The Max Distance Change threshold (red lines) adapts based on the previous Raw Measurement sample (blue lines) as long as that sample was within the previous thresholds.

B. The temporary distance spike in the Raw Measurement (blue lines) is filtered out because the distance increase was outside of the Max Distance Change (red lines). The Output Measurement (green lines) will hold its last measurement.

C. The Raw Measurement change (blue lines) is greater than the Max Distance Change (red lines) so the Output Measurement (green lines) holds its previous value while the Raw Measurement is beyond the Max Distance Change. After the 1 second Hold Time expires, the Output Measurement and Max Distance Change thresholds are updated based on the next Raw Measurement value.

D. The Raw Measurement (blue lines) drops down to a value below the Max Distance Change (red lines) so the Output Measurement (green lines) holds its value for the Hold Time. After the 1 second Hold Time expires, the Output Measurement and Max Distance Change thresholds are updated based on the next Raw Measurement value.

6 Specifications

Range
The sensor can detect an object at the following ranges, depending on the material of the target:
1515 models:

Detection Range: 0.15 m to 15 m (0.5 ft to 49.2 ft)
Measurement Range: 0.3 m to 15 m (1.0 ft to 49.2 ft)

Operating Principle
Frequency modulated continuous-wave (FMCW) radar

Operating Frequency
122 GHz

Supply Voltage (Vcc)
Analog Voltage models: 12 V DC to 30 V DC
Analog Current and Dual Discrete models: 10 V DC to 30 V DC
Use only with a suitable Class 2 power supply (UL) or Limited Power Supply (CE)

Power and Current Consumption, exclusive of load
Power consumption: < 2.4 W
Current consumption: < 100 mA at 24 V DC

Supply Protection Circuitry
Protected against reverse polarity and transient overvoltages

Linearity [3]
< ± 4 mm

Delay at Power-up
< 300 ms

Output Configuration
Analog Outputs:
·**Current models**

Discrete Output (Black Wire): IO-Link, push/pull output, configurable PNP or NPN output
Analog output (White Wire): 4 mA to 20 mA

·**Voltage models**

Discrete Output (Black Wire): IO-Link, push/pull output, configurable PNP or NPN output
Analog output (White Wire): Configurable 0 V to 10 V or 0.5 V to 4.5 V

·**Dual Discrete models**

Discrete Output 1 (Black Wire): IO-Link, push/pull output, configurable PNP or NPN output
Discrete Output 2 (White Wire): Configurable PNP or NPN, or Pulse Frequency Modulated (PFM) output

Repeatability [4]
< 1 mm

Maximum Output Power
EIRP: 100 mW, 20 dBm

Output Protection
Protected against output short-circuit

Remote Input
Allowable Input Voltage Range: 0 to Vsupply
Active High (internal weak pull-down): High state > (Vsupply - 2.25 V) at 2 mA maximum
Active Low (internal weak pull-up): Low state < 2.25 V at 2 mA maximum

Response Time
Analog update rate: 2 ms
Discrete output response: 6 ms
Speeds given for fast mode.

Indicators
Power LED: Green, power on
Signal Strength LED:

Red Flash: weak signal
Red Solid: 4× threshold

Output LEDs: Amber, target within taught analog span/discrete output status
NO/NC LED: Amber, normally open/normally closed status of discrete output
See Figure 2 on p. 4

Construction
Housing: PBT
Window: COP

Connections
Integral M12/Euro-style quick disconnect
150 mm (6 in) PUR cable with a M12/Euro-style quick disconnect
Models with a quick disconnect require a mating cordset

Vibration and Mechanical Shock
All models meet MIL-STD-202F, Method 201A (Vibration: 10 Hz to 60 Hz maximum, 0.06 inch (1.52 mm) double amplitude, 10G acceleration) requirements. Method 213B conditions H&I.Shock: 75G with device operating; 100G for non-operation

Operating Temperature
–40 °C to +65 °C (–40 °F to +149 °F)

Temperature Effect
< ± 10 mm from –40 °C to +65 °C (–40 °F to +149 °F)

Environmental Rating
IEC IP67

[3] At ranges ≥ 0.5 m, from 0.3 m to 0.5 m, linearity ≤ ±15 mm. Reference target with RCS = 1m²
[4] Repeatability < 10 mm at Excess Gain < 10×.

Output Ratings

Analog Outputs:
· **Current Output (T30R….-.I.. models):** 1 kΩ maximum load resistance at 24 V; maximum load resistance = [(Vcc - 4.5)/0.02 Ω]
· **Voltage Output (T30R….-.U.. models):** 2.5 kΩminimum load resistance
Discrete Outputs:
· **Current rating = 50 mA maximum each**

Black wire specifications per configuration		
IO-Link Push/Pull	Output High	≥ Vsupply - 2.5 V
	Output Low	≤ 2.5V
PNP	Output High	≥ Vsupply - 2.5 V
	Output Low	≤ 1V (loads ≤ 1 MegΩ)
NPN	Output High	≥ Vsupply - 2.5 V
	Output Low	≤ 2.5 V

White wire specifications per configuration		
PNP	Output High	≥ Vsupply - 2.5 V
	Output Low	≤ 2.5 V (loads ≤ 70 kΩ)
NPN	Output High	≥ Vsupply - 2.5 V
	Output Low	≤ 2.5 V

Certifications

UL Environmental Rating: Type 1

ETSI EN 305 550-1 V.1.2.1; ETSI EN 305 550-2 V.1.2.1; FCC/CFR-47 part 18; for others, contact Banner Engineering
Country of Origin: USA

6.1 PC Requirements

Operating System
Microsoft® Windows® operating system version 10 [5]

Hard Drive Space
500 MB

Third-Party Software
.NET

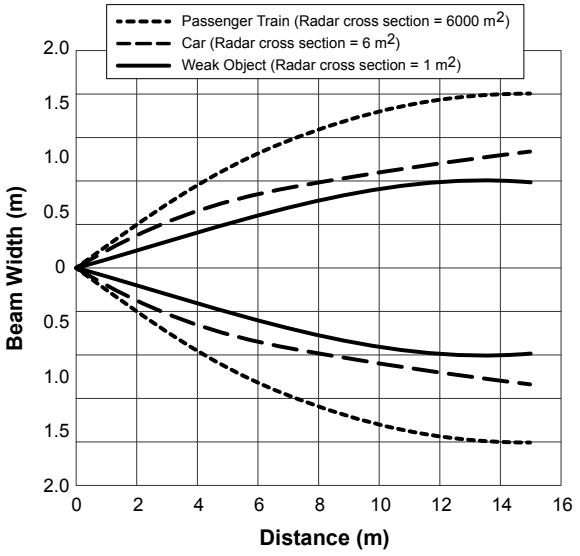
USB Port
Available USB port

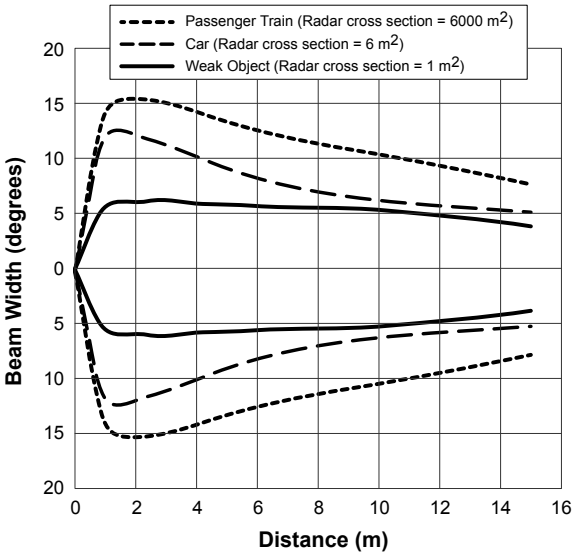
Important: Administrative rights are required to install the Banner Radar Configuration software.

[5] Microsoft and Windows are registered trademarks of Microsoft Corporation in the United States and/or other countries.

6.2 Beam Patterns

The effective beam pattern depends on the signal strength threshold and the properties of the target. The following beam patterns are shown with Signal Strength Threshold = 1.

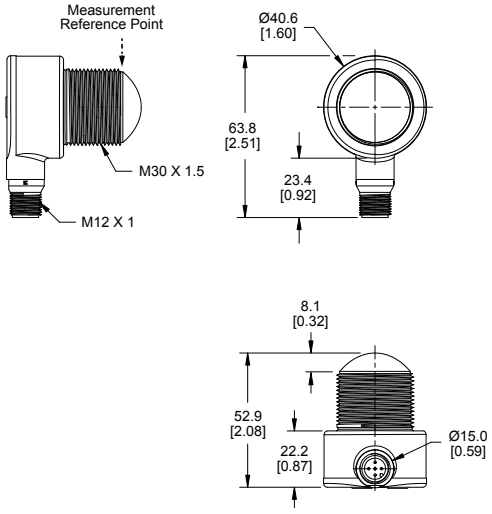




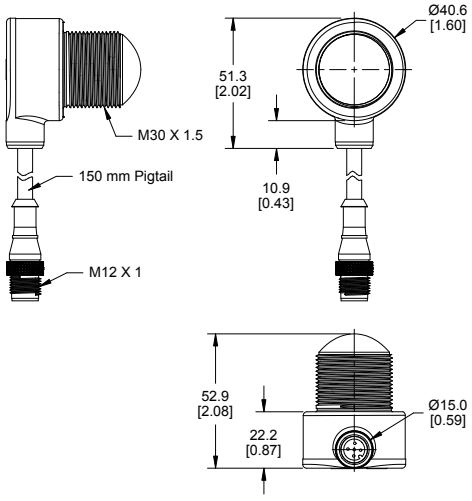
6.3 Dimensions

All measurements are listed in millimeters [inches], unless noted otherwise.

Integral QD Models



150 mm QD Models

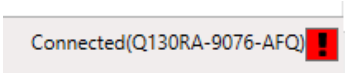


7 Update the Software

Use this procedure to update the Banner Radar Configuration Software.

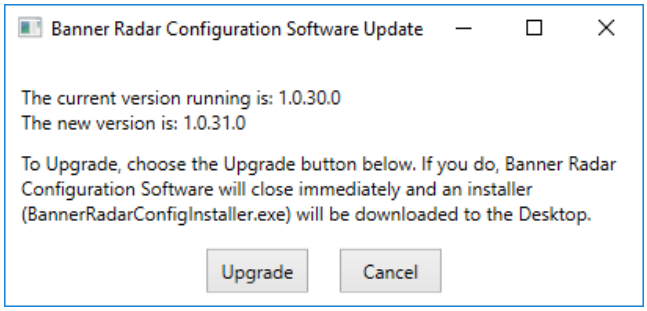
The Banner Radar Configuration Software automatically looks for updated software versions. The symbol in the lower right corner indicates that a software update is available.

Figure 12. Software Update Available



1. Click in the lower right corner of the software.
   The Banner Radar Configuration Software Update screen displays.

Figure 13. Banner Radar Configuration Software Update Screen



2. Click **Upgrade** to begin the process.
   The Banner Radar Configuration Software closes and an installer (BannerRadarConfigInstaller.exe) downloads to the desktop.

Note: If changes have not been written to the sensor, the system asks whether you want to exit the program. Click **No** to stop the update process and return to the Software. Write the changes to the sensor, then return to step 1, above, to update the Software.

3. Navigate to and open the file BannerRadarConfigInstaller.exe.
4. Depending on your system settings, a popup window may appear prompting to allow Banner Radar Configuration Software to make changes to your computer. Click **Yes**.
5. Click **Close** to exit the installer.

The software update is complete.

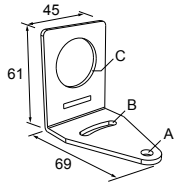
8 Accessories

8.1 Brackets

All measurements are in mm

SMB30A

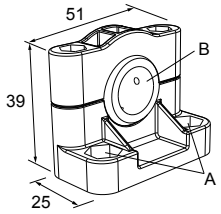
- Right-angle bracket with curved slot for versatile orientation
- Clearance for M6 (¼ in) hardware
- Mounting hole for 30 mm sensor
- 12-ga. stainless steel



Hole center spacing: A to B=40
Hole size: A=ø 6.3, B= 27.1 x 6.3, C=ø 30.5

SMB1815SF

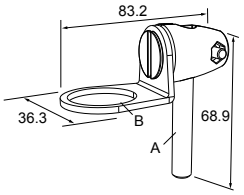
- Swivel with set screws for mounting sensors by the cable hub
- Black reinforced thermoplastic polyester
- Stainless steel swivel locking hardware and hex wrench included



Hole center spacing: A = 36.0
Hole size: A = ø 5.0, B = ø 15.0

SMB30FA

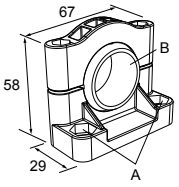
- Swivel bracket with tilt and pan movement for precise adjustment
- Mounting hole for 30 mm sensor
- 12-ga. 304 stainless steel
- Easy sensor mounting to extrude rail T-slot
- Metric and inch size bolt available



Bolt thread: SMB30FA, A= 3/8 - 16 x 2 in; SMB30FAM10, A= M10 - 1.5 x 50
Hole size: B= ø 30.1

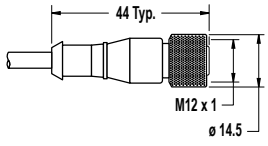
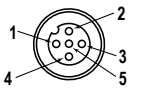
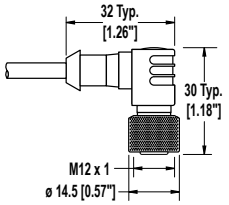
SMB30SC

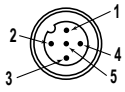
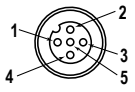
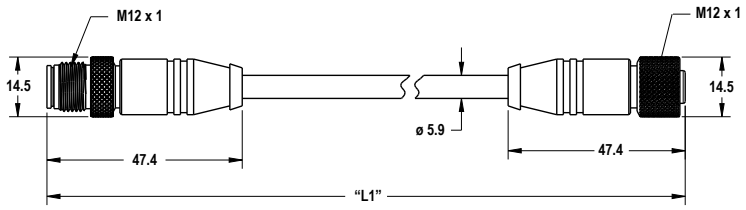
- Swivel bracket with 30 mm mounting hole for sensor
- Black reinforced thermoplastic polyester
- Stainless steel mounting and swivel locking hardware included

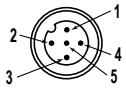
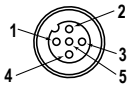
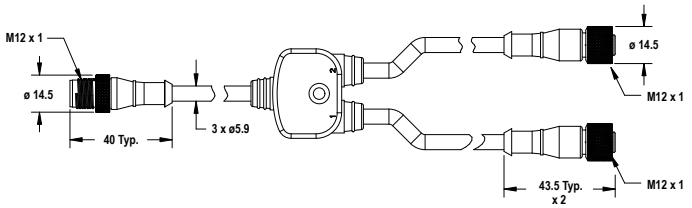


Hole center spacing: A=ø 50.8
Hole size: A=ø 7.0, B=ø 30.0

8.2 Cordsets

5-Pin Threaded M12/Euro-Style Cordsets with Shield—Single Ended				
Model	**Length**	**Style**	**Dimensions**	**Pinout (Female)**
MQDEC2-506	2 m (6.56 ft)	Straight		 1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray
MQDEC2-515	5 m (16.4 ft)			
MQDEC2-530	9 m (29.5 ft)			
MQDEC2-550	15 m (49.2 ft)			
MQDEC2-506RA	2 m (6.56 ft)	Right-Angle		
MQDEC2-515RA	5 m (16.4 ft)			
MQDEC2-530RA	9 m (29.5 ft)			
MQDEC2-550RA	15 m (49.2 ft)			

5-Pin Male Threaded and 5-Pin Female Quick Disconnect M12/Euro-Style Cordset with Shield—Double Ended				
Model	**Length "L1"**	**Style**	**Pinout (Male)**	**Pinout (Female)**
MQDEC3-503SS	0.91 m (2.99 ft)	Female Straight/Male Straight		
MQDEC3-506SS	1.83 m (6 ft)			
MQDEC3-515SS	4.58 m (15 ft)			
MQDEC3-530SS	9.2 m (30.2 ft)			
			1 = Brown 2 = White 3 = Blue	4 = Black 5 = Gray

5-Pin Threaded M12/Euro-Style Splitter Cordset with Flat Junction				
Model	**Trunk (Male)**	**Branches (Female)**	**Pinout (Male)**	**Pinout (Female)**
CSB-M1251M1251B	0.3 m (0.98 ft)	0.3 m (0.98 ft)		
			1 = Brown 2 = White 3 = Blue	4 = Black 5 = Gray

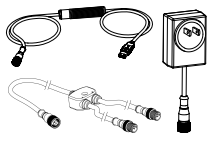
Note: The splitter in the PRO-KIT has two male and one female connectors. The CSB-M1251M1251B splitter has one male and two female connectors. Use the CSB-M1251M1251B to connect the sensor to power and a one of the Banner Pro lights with the Pulse Pro output.

8.3 Configuration Tool

PRO-KIT

Includes:

- Pro Converter Cable (MQDC-506-USB)
- Splitter (CSB-M1251FM1251M)
- Power Supply (PSW-24-1)



9 Product Support and Maintenance

9.1 Repairs

Contact Banner Engineering for troubleshooting of this device. **Do not attempt any repairs to this Banner device; it contains no field-replaceable parts or components.** If the device, device part, or device component is determined to be defective by a Banner Applications Engineer, they will advise you of Banner's RMA (Return Merchandise Authorization) procedure.

Important: If instructed to return the device, pack it with care. Damage that occurs in return shipping is not covered by warranty.

You may be asked to provide the configuration file and the data log file (.cfg) to aid in troubleshooting.

9.2 Contact Us

Banner Engineering Corp. headquarters is located at:

9714 Tenth Avenue North
Minneapolis, MN 55441, USA
Phone: + 1 888 373 6767

For worldwide locations and local representatives, visit www.bannerengineering.com.

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