### **Quotation Bill of Material**

#### Item Qty Product Information

1 1 ACS880-07-0503A-5+B054+C129+C196 ACS880 Drive Cabinet Drive (07). Input Voltage 480 VAC. 483A LD, 361A HD. IP42 - UL type 1 +B054. Frame Size -R10

#### Terms:

- FOB ABB Factory
- Proposal valid for 30 days from quotation date
- ABB Inc. Standard Terms and Conditions of Sale apply
- Proposal based upon acceptance of Clarifications and Exceptions to Specifications and Terms provide later in this quotation

### Submittal Schedule

Schedule			Motor Data <sup>1</sup>		ta <sup>1</sup>	Drive Data			
Item	Qty	Тад	HP	FLA	Volts	Product ID	HP	Amps	Volts
1	1		400	503	460 VAC	ACS880-07-0503A- 5+B054+C129+C196	400	483A LD, 361A HD	480 VAC
Notes	Notes:       1. AC motor data is per National Electrical Code Table 430.250 for typical motors used in most applications. It is provided as typical data only. DC motor data is per typical industry standards. Actual motor data may vary								

This schedule includes the products supplied as part of this submittal.

# Clarifications and Exceptions to Specification and Terms

The comments and clarifications that follow are offered in response to the specification items identified below. Please refer to the specification section and paragraph indicated. Any contract executed based on this proposal is done based acceptance of the exceptions noted herein.

Item ID	Title	Clarifications and Exceptions

#### Submittal Schedule Details for

Item	Tag / Equipment ID	Product ID
1		ACS880-07-0503A-5+B054+C129+C196

Item Description
Input Voltage: 480 VAC Rated Output Current: 483A LD, 361A HD AMPS Enclosure: IP42 - UL type 1 +B054 Nominal Horsepower: 400 Frame Size: R10 Input Disconnecting Means: Main switch Bypass: None Input Impedance:
<ul> <li>3% Nominal Impedance, R1-R9, DC Bus Choke; R10 and greater, AC Reactor</li> <li>Short Circuit Current Rating: 100 kA symmetrical amperes (rms) at 600 V max when protected with T-class fuses</li> <li>Communication Protocols:</li> <li>FieldBus Communication Options:</li> </ul>
<ul> <li>Other Options:</li> <li>Construction Options:</li> <li>UL-listed [Includes US type main switch fuse, top cable entry (H351), top cable exit (H353) and US cable conduit entry (H358). All components are UL-listed/ recognized, maximum supply voltage is 600 V] +C129</li> <li>Empty 400 mm cabinet on right side +C196</li> <li>Cabling Options:</li> <li>Top cable entry [Included with UL-listed (C129) option] (+H351)</li> <li>Top cable exit [Included with UL-listed (C129) option] +H353</li> <li>Software Options:</li> <li>Primary Control Program</li> <li>Documentation Options:</li> <li>USB Stick (std)</li> </ul>

Drive Input Fuse Ratings				
Fuse Class	Amps (600 V)			
170M6412 Class 3	800			

Wire Size Capacities of Power Terminals						
Input Wiring	Output Wiring	Ground Wiring				
Busbar for use with 2 hole lugs (7/16" bolt x 1.75" spacing) 3755 lb-ft	Busbar for use with 2 hole lugs (7/16" bolt x 1.75" spacing) 3755 lb-ft	Busbar for use with 1 hole lugs (3/8" bolt) 2232 lb-ft				

Dimensions and Weights				
Height	Width	Depth	Weight	
in	in	in	<i>Ibs</i>	
(mm)	(mm)	(mm)	(kg)	
84.5	48.5	27.5	1520	
(2145)	(1230)	(698)	(690)	

Heat Dissipation & Airflow Requirements			
Power Losses	Airflow		

BTU/Hr	Watts	CFM	CM/Hr
20821	6102	1837	2950

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### ACS880-07 Product Overview

### *Description* Cabinet-built single drives, ACS880-07

Our cabinet-built single drives are built to order, meeting customer needs despite any technical challenges. Designed on ABB's common drives architecture, this compact drive comes in twelve different sizes (R6 to R11, nxD8T+nxR8i) for easy installation and commissioning.

These single drives are customized to the precise needs of industries such as oil and gas, mining, metals, chemicals, cement, power plants, material handling, pulp and paper, woodworking and marine. Typical applications include cranes, extruders, winches, conveyors, mixers, compressors, pumps and fans. The drive configuration contains a rectifier, DC link and an inverter, all built into a compact cabinet.

At the heart of the drive is direct torque control (DTC), ABB's premier motor control technology. The drive can control the motors in either open loop or closed loop. Induction motors, synchronous motors and induction servo motors are all supported as standard without the need for additional software.

#### Drive Module Main features include

- Incoming air temperature measurement for protecting the drive from different temperature related failure mechanisms
- Integrated safety including safe torque-off (STO) as standard (TÜV Nord certificate)
- Supports various motor types including: Asynchronous induction and synchronous PM motors,
- Removable memory unit for easy maintenance
- Primary control program common software used throughout the ACS880 drive series
- Control unit supporting a wide range of fieldbuses, feedback devices and input/output options
- Coated boards as standard
- Controllable cooling fan
- Built-in DC choke

#### Standard Main Cabinet features include (with +C129 UL Option)

- Compact design for easy cabinet assembly and maintenance
- Intuitive and easy to operate control panel with USB connection
- Cabling : top entry and exit cabling
- Enclosure class UL Type1 (IP22)
- Solid removable 3mm cable conduit plate
- Disconnect Switch with rotary through the door handle
- Fast acting UL fuses



#### **Applications:**

- Constant Torque, Variable Torque or Constant Horsepower applications.
- New installation, replacement and original equipment manufacturer (OEM) use.

#### Features:

• DTC or Scalar (V/Hz) control with peak overload of 150% for performance applications. Flexible enclosure drive options, built to order with 2 enclosure classes. ABB's all compatible keypad, programming structure and drive options. Designed for demanding applications with: high starting torque, speed and torque accuracy, flexible programming and certified safety options.

### ACS880 Standard Features

**Standard Features** UL and cUL (requires +C129 option selection) **Graphical Multilingual Display** Graphical Metering and Trending on Display Intelligent Start-Up Assistant Motor ID Run Motor Control Direct Torque Control (DTC) Scalar Control Input Fuses and Disconnect Two (2) Programmable Analog Inputs Six (6) Programmable Digital inputs Two (2) Programmable Digital Inputs/Outputs One (1) Digital Input InterLock (DIIL) Two (2) programmable Analog Outputs Three (3) Programmable Form C Relay Outputs Dual Input Safe Torque Off (STO) Three (3) Expansion Slots for Fieldbus (communication), I/O and Motor Feedback Modules Adjustable Filters on Analog Inputs and Outputs Input Speed Signals Two (2) Voltage +/- 0(2)-10 Vdc / Current 0(4)-20 mA Increase/Decrease Reference Contacts Fieldbus Adapters (communication modules) Start/Stop 2-wire Control (dry contact closure) 3-wire Control (momentary dry contacts) Adjustable Current Limit Adjustable Torque Limit Three (3) Supervision Functions **Electronic Reverse** Power Loss Ride-Through DC Magnetizing Start (provides max starting torque) DC Hold Flux Braking Energy (flux) Optimization Seven (7) Preset Constant Speeds Three (3) Critical Speed Lockout Bands Automatic Reset Customer Selectable Two (2) Independently Adjustable Accel and Decel Ramps Linear or Adjustable "S" Curve Accel/Decel Ramps Ramp to Stop or Coast to a Stop Maximum Output Frequency Programmable up to 500 Hz Two (2) Integral Programmable PID Setpoint Controller Mathematical Functions on Analog Reference Signals Reactor with ~3% impedance - DC (R6-R9) Optional Integral Brake Chopper (R6-R11) Reference Trim Programmable Mechanical Brake Control Master/Follower Load Analyzer Two (2) Jogging functions

#### **Programmable Fault Functions** Al<Min Panel Loss Four (4) External Fault Motor Thermal Protection Motor Stall Under Load Motor Phase Loss Ground Fault **Communications Fault** Supervision of Optional I/O Cross Connection (Input/Output Power Wiring) External Temperature Measurement Preprogrammed Protections: Över current Short Circuit Over Voltage (Intermediate Circuit) Under Voltage (Intermediate Circuit) Input Phase Loss Ambient Temperature Drive Over Temperature Internal Fault Over Speed Brake Resistor Available options I/O Option Modules DDCS Communications Analog I/O Extension Digital I/O Extension HTL Pulse Encoder Interface TTL Pulse Encoder Interface **Resolver Interface** Absolute Encoder Interface Fieldbus Adapter Modules DeviceNet<sup>†</sup>M ProfiBus-DP™ ModBus™ ConrolNet™ Ethernet (EIP, PROFINET, MB/TCP) EtherCat® CANOpen Dynamic Braking Choppers (R6 Frame and Up) CE EMC Filters (1st and 2nd Environments) Drive Composer PC Tool (available for download) Drive Composer Pro PC Tool

**Application Software options** 

Primary Control Program

### ACS880 Specifications

#### Input Connection

Input Voltage Input Frequency Line Imbalance Fundamental Power Factor (cosphi1) Connection

#### **Output Connection**

Output Voltage Output Frequency **Continuous Current** 

Short Term Overload Capacity

Peak Overload Capacity Field Weakening Point Switching Frequency

Efficiency Short circuit withstand rating Connection

#### **Ambient Conditions, Operation**

Air Temperature

**Relative Humidity** 

**Contamination Levels** IEC **Chemical Gasses** Solid Particles Installation Site Altitude

Vibration Max

### Ambient Conditions, Storage & Transportation (in Protective Shipping Package)

Air Temperature Relative Humidity Atmospheric Pressure Vibration Max

Shock (IEC 60068-2-29) Free Fall

#### **Cooling Information**

Cooling Method Power Loss

Internal Fan Approximately 2% of rated power

-40° to 70°C (-40° to 158°F)

5 to 95%, no condensation allowed

70 to 106 kPa (10.2 to 15.4 PSI)

Max 100 m/s<sup>2</sup> (328 ft/s<sup>2</sup>) 11 ms

#### Auxiliary Power Supply (XD 24:2 and XD 24:4) 24 Vdc, +/-10%

Voltage Maximum Current Protection

200 mA - minus load taken by DIO1 and DIO2 Short Circuit Protection

100 mm (4 in) for weight greater than 100 Kg (220 lb)

#### **Control Terminal Blocks**

#### **Analog Inputs**

Two (2) Programmable Differential Inputs Two (2) Current or Voltage Signals

Common Mode Voltage Common Mode Rejection Ratio Resolution Accuracy Input Updating Time **Optional Isolation** 

0(4) to 20 mA, Input Resistance RI => 100 ohms or -10 Vdc / 0(2) to +10 Vdc, Input Resistance RI =>200 kohm +/-15 Vdc, max. > 60 dB at 50 Hz 0.025% (12 bit) (11 bit + Sign bit) +/-0.5% of Full Scale Range 1 ms (Primary Control Program)

Size 0.5...2.5 mm<sup>2</sup> (24...12 AWG) - All control terminal blocks Tightening torques: 0.5 N•m (5 lbf•in) for both stranded and solid wiring

Available through optional external module

42930712

380-690 Vac 3-phase, +10%...-15% (R6-R11) or +/-10% (nxR8i) 47 to 63 Hz, maximum rate of change 17 %/s Max +/-3% of nominal phase to phase input voltage 0.98 (at nominal load) U1, V1, W1

0 to U<sub>1</sub>, 3-phase symmetrical, U<sub>max</sub> at the field weakening point 0..500 Hz I2Ld (light duty use) I2hd (heavy-duty use) I2Ldmax = 1.1 \* I2Ld (1 min / 5 minutes @ 40°C), typical Ihdmax = 1.5 \* I2hd (at least 1 min / 5 min @ 40°C) Imax (400 Vac and 500 Vac) (at least 10 seconds at start) 8 to 500 Hz DTC dynamically varies from 1 to 12 kHz 2.7 kHz (typical) for R6-R9 3 kHz (typical) for R10-R11 2 kHz (typical) for nxR8i 98% at nominal power level 100,000 AIC (UL) when protected by fuses given in the hardware manual U2, V2, W2

0° to 40°C (104°F), above 40°C the rated output current is de-rated 1% for every additional 1°C [up to 50°C (122°F)] 5 to 95%, no condensation allowed, maximum relative humidity is 60% in the presence of corrosive gasses

60721-3-1, 60721-3-2 and 60721-3-3 Class 3C2 Class 3S2 0 to 1000 m (3281 ft) above sea level. At sites over 1000 m (3281 ft) above sea level, the maximum power is de-rated 1% for every additional 100 m (330 ft). Maximum altitude 4000 m (13123 ft) above sea level. 1 mm (0.04 in) @ 5 to 13.2 Hz, 7 m/s<sup>2</sup> (23 ft/s<sup>2</sup>) @ 13.2 to 100 Hz for R6-R11 0.075 mm (0.003 in) @ 10 to 57 Hz, 1 g @ 57 to150 Hz for nxR8i

3.5 mm (0.14 in) @ 2 to 9 Hz, 15 m/s2 (49 ft/s2) 9 to 200 Hz for R6-R11 3.5 mm (0.14 in) @ 2 to 9 Hz, 10 m/s<sup>2</sup> (32.8 ft/s<sup>2</sup>) 9 to 200 Hz for nxR8i

### ACS880 Specifications (cont.)

#### **Reference Power Supply**

Voltage Maximum Load Applicable Potentiometer +10 Vdc, 0 Vdc, -10Vdc +/- 0.5% at 25°C (77°F) 10 mA 1 kohm to 10 kohm

#### **Analog Outputs**

Two (2) Programmable Current Outputs Signal Level Resolution Accuracy Maximum Load Impedance Output Updating Time Frequency Range

0(4) to 20 mA 0.025% (12 bit) (11bit +Sign Bit) +/-1% Full Scale Range 500 ohm 1 ms (Primary Control Program) 0 ... 300 Hz

#### **Digital Inputs**

Six (6) Programmable Digital Inputs (Common Ground), plus One (1) Start Interlock Isolation Isolated 500 Vac, 1 minute Isolation Test Voltage Input Type NPN/PNP (DI1...DI5), NPN (DI6) Signal Level 24Vdc Rin 2.0 kohm Logical switch thresholds <5 Vdc at "0", >15 Vdc at "1" Input Current 15 mA (DI1...DI5), 5 mA (DI6) Filtering Time Constant Hardware Filter 0.04 ms Input Updating Time Digital Filtering up to 8 ms (Primary Control Program) Frequency Range ...... 0 ... 300 Hz

#### **Digital Inputs/Output**

 Two (2) Programmable Digital Inputs/Outputs

 Isolation
 Isolated

 Input Configuration
 DIO1 frequency input (0...16 KHz with 4 microsecond hardware filtering)

 Output Configuration
 DIO2 frequency output (0...16 KHz with 4 microsecond hardware filtering)

 Signal Level
 24 Vdc

 Rin
 2.0 kohm

 Logical input switch thresholds
 <5 Vdc at "0", >15 Vdc at "1"

 Filtering Time Constant
 0.25 ms

 As output
 Total output current from +24Vdc is limited to 200 mA

#### Safe Torque Off Connection

#### Internal 24 Vdc Supply for Digital Inputs

Voltage24 VdcMaximum Current200 mAConnectorXD24:2 and XD24:4ProtectionShort Circuit ProofAn external 24 Vdc supply may be used instead of the internal supply

#### **Relay Outputs**

Three (3) Programmable Relay Outputs Switching Capacity Protection Maximum Continuous Current Output Updating Time

#### Protections

Single Phase Over Voltage Trip Limit Under Voltage Trip Limit Over Temperature Auxiliary Voltage Ground Fault Motor Stall Protection Motor Over Temperature Cross Cable Connection 2 A at 30 Vdc or 250 Vac Varistors (250 V) IC = 2  $A_{rms}$ 1 ms (Primary Control Program)

Protected (input & output) 1.3 \* U1max 0.65 \* U1min Protected Short Circuit Protected Protected Protected Protected (I2t) Protected

### ACS880 control Panel

The ACS880 assistant control panel features a graphical display for easy drive configuration. The LCD type display has a monochrome  $240 \times 160$  pixel resolution with a white backlight. The language is selected at start-up (parameter 96.01).

It is an ideal tool for users and service technicians that provides the following features."



### Ease of Navigation and Start Up

The control panel is intuitive to use and includes multiple home views with graphical displays for quick visual feedback of the motor and drive status. The soft keys allow for easy navigation through the drive's menu system.

Exit	10:02	Edit
Motor nomin	nal voltage:	400 V
Motor nomin	nal current	31.0 A
Motor type:	Perm. ma	ignet (PM)
Check the v nameplate,	alues from th and enter the	ne motor's em here.
<ul> <li>Motor d</li> </ul>	ata	0 >
Local 🦿 A	ACS880	1400.0 Rpm

The ACS880 control panel features a set-up assistant that prompts the user through the commissioning process. It navigates thorough the parameters that pertain to initial set up and allows easy entry of motor and line settings. It then allows the selection of different ID run procedures, including normal rotation, reduced rotation, and without rotation, and to customize selections based on the existing conditions.





- 1. Use a separate grounding PE cable (1a) or a cable with a separate PE conductor, follow local codes for cable size
- 2. 360-degree grounding is recommended if shielded cable is used. Ground the other end of the input cable shield or PE conductor at the distribution board.
- 3. 360-degree grounding is required using shielded cable or conduit.
- 4. Line contactor (option +F250)
- 5. Common mode filter (option +E208)
- 6. du/dt filter or sine filter (options +E205 and +E206)
- 7. Use a separate grounding cable if there is no symmetrically constructed grounding conductor in the cable.
- 8. External brake resistor
- 9. Terminals of frame R9 cabinet:

	UDC+	
R-	R+	UDC-

10. Drive module

![](_page_12_Figure_0.jpeg)

![](_page_12_Figure_1.jpeg)

![](_page_14_Figure_0.jpeg)

![](_page_15_Figure_0.jpeg)

![](_page_16_Figure_0.jpeg)

### Default I/O connection diagram (Factory Macro)

Transianal Daviana	POW E	External p	power input
/ Typical External Devices	1	+24VI	241/ DC 24
Not Included		GND	24 V DC, 2 R
ن i ک	XAI F	Referenc	e voltage and analog inputs
	1	+VREF	10 V DC, R <sub>L</sub> 110 kohm
	2	-VREF	-10 V DC, R <sub>L</sub> 110 kohm
╡ ╡ く く く し く し く し く	3	AGND	Ground
	4	Al1+	President and and a second sec
	5	AI1-	Speed reference U(2)10 V, R <sub>in</sub> > 200 konm <sup>17</sup>
; <u>-</u>	6	AI2+	Du default act in une 2000 - 20 mil 20 - 400 et m <sup>2</sup>
	7	AI2-	By delault not in use. 0(4)20 mA, R <sub>in</sub> > 100 0nm ->
i i i	J1	J1	AI1 current/voltage selection jumper
! !	J2	J2	AI2 current/voltage selection jumper
i X	AO /	Analog o	utputs
	1	A01	Mater aread run 0, 20 mil 0, < 500 chm
	2	AGND	<b>Motor speed (pm</b> 020 mR, $R_{\rm L}$ < 500 mm
	3	A02	Mater everyont 0, 20 mill (2, 7 500 altre
	4	AGND	Motor current 020 mA, RL < 500 onm
¦ <sup>™</sup> = '   XI	D2D [	Drive-to-i	drive link
i i	1	в	
!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	2	A	Drive-to-drive link
i i	3	BGND	
!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	J3	J3	Drive-to-drive link termination switch
XF	R01, X	RO2, XF	RO3 Relay outputs
! !	1	NC	Ready
	2	COM	250 V AC / 30 V DC
	3	NO	2A 2A
	1	NC	
	2	COM	250 V AC / 30 V DC
╎╵──┼╦╢──╎	3	NO	2A 2A
	1	NC	F aulted(-1)
	2	COM	250 V AC / 30 V DC
i i i	3	NO	2A
	D24 [	Digital int	erlock
i   i	1	DIIL	Digital start interlock
; I I ;	2	+24VD	+24 V DC 200 mA <sup>3)</sup>
i i i	3	DICOM	Digital input ground
	4	+24VD	+24 V DC 200 mA <sup>3)</sup>
i – totali	5	DIOGN	Digital input/output ground
	J6 (	Ground s	election switch
· · · · · · · · · · · · · · · · · · ·	DIO [	Digital in	put/outputs
	1	DI01	Output: Ready
. i 🗌	2	DIO2	Output: Running
	XDI [	Digital inj	outs
	1	DI1	Stop (0) / Start (1)
	2	DI2	Forward (0) / Reverse (1)
	3	DI3	Reset
	4	DI4	Acceleration & deceleration select <sup>4)</sup>
5 6 XSTO 		DI5	Constant speed 1 (1 = On) の
		DI6	By default not in use.
		Safe toro	que off
		OUT1	
		SGND	Safe targue off. Both circuits must be closed for the drive to start
		IN1	oale torque on, both circuits must be closed for the unvelop staft.
		IN2	
	<b>X 12</b> 8	Safety fu	nctions module connection
· · · · · · · · · · · · · · · · · · ·	<b>X 13</b> (	Control p	anel connection
×	(205	M emory (	unit connection

Control unit terminal wire sizes: 0.5...2.5 mm<sup>2</sup> (24...12 AWG). Tightening torques: 0.5 N·m (5 lbf·in) for both stranded and solid wiring

## **Engineering Data Summary**

### Replacement Fuses

Drive input fuses are recommended to disconnect the drive from power in the event that a component fails in the drive's power circuitry. Recommended drive input fuse specifications are listed in the *Submittal Schedule Details* and in the *Fuse Ratings* Table. Fuse rating information is provided for customer reference.

Item	Catalog Number	Drive Input Fuse Ratings		
		Amps (600V)	Bussmann Type	
1	ACS880-07-0503A- 5+B054+C129+C196	800	170M6412 Class 3	

### *Terminal Sizes / Cable Connection Requirements*

Power and motor cable terminal sizes and connection requirements are shown in the *Submittal Schedule Details* and in the *Terminal Sizes / Cable Connection Requirements* Table. The information provided below is for connections to input power and motor cables. These connections may be made to an input circuit breaker or disconnect switch, a motor terminal block, overload relay, and/or directly to bus bars and ground lugs. The table also lists torque that should be applied when tightening terminals and spacing requirements where multiple mounting holes are provided in the bus bar.

Item	Catalog Number	Input Wiring	Output Wiring	Ground Wiring
1	ACS880-07-0503A- 5+B054+C129+C196	Busbar for use with 2 hole lugs (7/16" bolt x 1.75" spacing) 3755 lb-ft	Busbar for use with 2 hole lugs (7/16" bolt x 1.75" spacing) 3755 lb-ft	Busbar for use with 1 hole lugs (3/8" bolt) 2232 lb-ft

### Heat Dissipation Requirements

The cooling air entering the drive must be clean and free from corrosive materials. The *Submittal Schedule Details* and the *Heat Dissipation Requirements* table below give the heat dissipated into the hot air exhausted from the drives. If the drives are installed in a confined space, the heat must be removed from the area by ventilation or air conditioning equipment.

Item	Catalog Number	Watts	BTU/Hr
1	ACS880-07-0503A- 5+B054+C129+C196	6102	20821

### **Dimensions and Weights**

Dimensions and weights of the drives provided are given in the *Submittal Schedule Details* and in the *Dimensions and Weights* Table. The table also lists the applicable dimension drawings that include additional detail. Dimension drawings may be provided in the back of this submittal.

Item	Catalog Number	Height mm (in)	Width mm (in)	Depth mm (in)	Weight <i>kg</i> (Ibs)
1	ACS880-07-0503A-	2145	1230	698	690
	5+B054+C129+C196	(84.5)	(48.5)	(27.5)	(1520)

### Product Short Circuit Current Rating

Short circuit ratings shown below are as show on the device rating label.

Item	Catalog Number	Short Circuit Current Rating
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Item	Catalog Number	Short Circuit Current Rating
1	ACS880-07-0503A- 5+B054+C129+C196	100 kA symmetrical amperes (rms) at 600 V max when protected with T-class fuses

Type code:ACS880-07-0503A-5+B054+C129+C196Colour:RAL 7035/RAL 9017Dimensions:millimeters (100mm=3.937")Weight:690 kgDegree of protection:IP42Cable entry type:Steel 3mm, undrilled

![](_page_20_Figure_1.jpeg)

A – A

![](_page_21_Figure_0.jpeg)