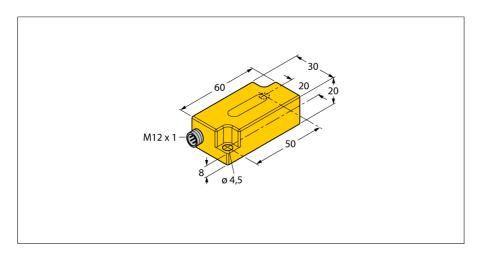
Single-axis inclinometer with 2 analog outputs B1N360V-Q20L60-2Li2-H1151





Ident-No. Ident-No (TUSA)	1534068 M1534068	
Repeatability	≤ 0.2 % of measuring range A - B	
	≤ 0.1 %, after warm-up 0.5 h	
Temperature coefficient typical	0.03 °/K	
Resolution	≤ 0.14 °	
Ambient temperature	-30+70 °C	

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justed measuring range

Operating voltage 10...30VDC Rated insulation voltage $\leq 0.5 \; kV$ Short-circuit protection ves

Wire breakage / Reverse polarity protection yes/ complete 5-pin, analog output Output function Current output 4...20mA

2 outputs, one for CW and one for CCW Load resistance, current output $\leq 0.2~k\Omega$

Response time 0.1 sTime for the output signal to reach 90% of the ad-

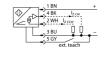
Current consumption 50...105 mA (voltage-dependent)

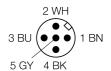
Construction rectangular, Q20L60 60 x 30 x 20 mm Dimensions plastic, PC Housing material Connection male, M12 x 1 Vibration resistance 55 Hz (1 mm) Shock resistance 30 g (11 ms) IP68 / IP69K IP Rating

MTTF 203 years acc. to SN 29500 (Ed. 99) 40 °C

- Rectangular, plastic, PC
- **Compact housing**
- Connection via M12x1 plug connectors
- 12 bit resolution
- 10...30 VDC
- Two counter-running 4 ... 20mA analog outputs improve machine safety through redundancy

Wiring diagram



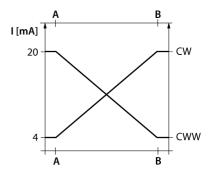


Functional principle

The TURCK inclinometers incorporate a micromechanical pendulum, operating on the principle of MEMS technology (Mikro Elektro Mechanic Systems).

The pendulum basically consists of two 'plate' electrodes arranged in parallel with a dielectric placed in the middle. When the sensor is inclined, the dielectric in the middle moves, causing the capacitance ratio between both electrodes to change.

The downstream electronics evaluates this change in capacitance and generates a corresponding output signal.



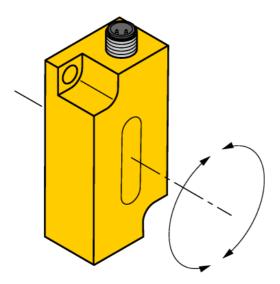
Type code

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Mounting instructions / Description

Tilt angle



Adjusting the measuring range via TX1-Q20L60 teach adapter

Setting the angular range in CW direction:

- Move sensor to start position
- Press and hold Teach-Gnd until the output is set to < 4 mA / 0,1 V (approx. 1 s)</p>
- Move sensor to end position
- Press and hold Teach-Gnd until the output is set to 20 mA / 4.9 V (approx. 3 s)

Resetting the angular range:

- Press and hold Teach-Gnd until the output is set to 12 mA (approx. 6 s)
- The working range of angle measurement is set back to 360° degrees (in position "connector outgoing topwards" the sensor provides an output signal in accordance with 0° degree)