AXL E PB DIO16 M12 6P

**Axioline E PROFIBUS device, plastic housing,
16 configurable inputs or outputs,
24 V DC, M12 connector**



Data sheet
8437_en_08

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1 Description

The Axioline E device is designed for use within a PROFIBUS network.
It is used to acquire and output digital signals.

PROFIBUS features

- Connection to PROFIBUS DP using M12 connectors (B-coded)
- DP/V1 for Class 1 and Class 2 masters
- Data transmission speed of 9.6 kbps up to 12 Mbps (automatic detection)
- Rotary encoding switches for setting the PROFIBUS address
- Supported PROFIBUS addresses 0 to 126
- PROFIBUS features: Sync mode, Freeze mode, I & M functions
- Device description using GSD file

Axioline E features

- Connection of digital sensors and actuators to M12 connectors (A-coded)
- Diagnostic and status indicators
- Short-circuit and overload protection of the sensor supply
- IP65/67 degree of protection

Observe this note

This data sheet is only valid in association with the corresponding documentation.
Make sure you always use the latest documentation.
It can be downloaded via the product at phoenixcontact.com/products.

2 Table of contents

1 Description 1
2 Table of contents 2
3 Ordering data 3
4 Technical data 4
5 Internal circuit diagram 8
6 Pin assignment 9
6.1 PROFIBUS and power supply connection 9
6.2 PROFIBUS pin assignment 9
6.3 Pin assignment of the power supply US/UA 10
6.4 Connecting inputs and outputs 10
6.5 Pin assignment of the inputs and outputs 10
7 Connection example 11
8 Connection notes 11
9 Configuration via rotary encoding switch 12
10 Local status and diagnostic indicators 13
10.1 Indicators for bus and power supply 13
10.2 Input and output indicators 14
11 Process data 15
11.1 Assignment of the terminal points to the IN process data 15
11.2 Assignment of the terminal points to the OUT process data 15
11.3 Status module 15
11.4 Configuration of digital inputs and outputs 15
12 Parameterization 16
13 I&M functions 17
14 Sync/freeze mode 18
15 Diagnostic alarms 18
16 Monitoring 18
17 Substitute value behavior 18

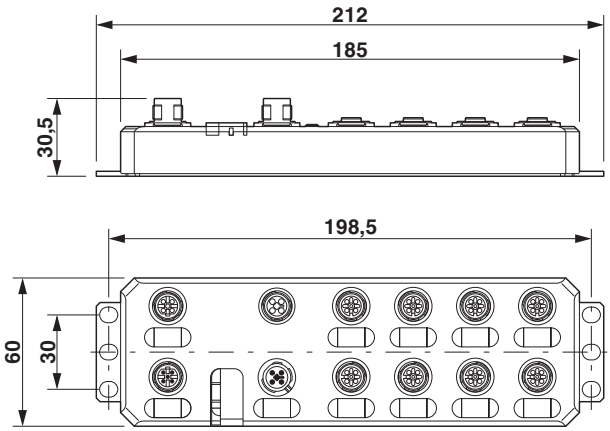
3 Ordering data

Description	Type	Item no.	Pcs./Pkt.
Axioline E, Digital I/O device, PROFIBUS DP, M12 connector, Digital inputs: 16, 24 V DC, connection technology: 4-conductor, Digital outputs: 16, 24 V DC, connection technology: 3-conductor, Plastic housing, degree of protection: IP65/IP67	AXL E PB DIO16 M12 6P	2701499	1

Additional ordering data	
For additional ordering data (accessories), go to:	www.phoenixcontact.com/product/2701499

4 Technical data

Dimensions (nominal sizes in mm)	



Width	60 mm
Height	185 mm
Depth	30.5 mm
Note on dimensions	The height is 212 mm including fixing clips.

General data	
Housing material	Pocan®
Color	anthracite
Weight	480 g
Ambient temperature (operation)	-25 °C … 60 °C

CAUTION: Risk of burns

If the device is used at an ambient temperature above 50°C, the contact temperature of metal surfaces can exceed 70°C.

Ambient temperature (storage/transport)	-25 °C … 85 °C
Permissible humidity (operation)	5 % … 95 %
Permissible humidity (storage/transport)	5 % … 95 %
Air pressure (operation)	70 kPa … 106 kPa (up to 3000 m above sea level)
Air pressure (storage/transport)	70 kPa … 106 kPa (up to 3000 m above sea level)
Degree of protection	IP65/IP67
Protection class	III (IEC 61140, EN 61140, VDE 0140-1)

Connection data	
Connection method	M12 connector

Interface: PROFIBUS DP	
Number	2
Connection method	M12 connector (B-coded)
Number of positions	5
Transmission speed	9.6 kbps ... 12 Mbps (Automatic baud rate detection)
Transmission physics	PROFIBUS-DP-compliant copper cable
PROFIBUS DP	
Equipment type	PROFIBUS slave
PROFIBUS protocols	DP V1
Module electronics, sensors and actuators (U_S)	
Connection method	M12 connector (T-coded)
Number of positions	4
Supply voltage	24 V DC
Supply voltage range	18 V DC ... 31.2 V DC (including all tolerances, including ripple)
Current consumption	typ. 165 mA ±15 % (at 24 V DC) max. 12 A
Supply of actuators (U_A) for additional devices	
Connection method	M12 connector (T-coded)
Number of positions	4
Supply voltage	24 V DC
Supply voltage range	18 V DC ... 31.2 V DC (including all tolerances, including ripple)
Current consumption	typ. 3 mA ±15 % (at 24 V DC) max. 12 A
Digital inputs	
Number of inputs	16
Connection method	M12 connector, double occupancy
Connection technology	4-conductor
Description of the input	EN 61131-2 types 1 and 3
Nominal input voltage	24 V DC
Nominal input current	typ. 3 mA
Sensor current per channel	typ. 75 mA (from U_S)
Total sensor current	max. 1.2 A (per device)
Input voltage range "0" signal	0 V DC ... 5 V DC
Input voltage range "1" signal	11 V DC ... 30 V DC
Input filter time	< 1000 µs
Cable length	max. 30 m (to the sensor)
Overload protection, short-circuit protection of sensor supply	yes

Digital outputs	
Number of outputs	16
Connection method	M12 connector, double occupancy
Connection technology	3-conductor
Nominal output voltage	24 V DC (from voltage U_S)
Output voltage range	18 V DC ... 31.2 V DC
Maximum output current per channel	500 mA
Nominal load, ohmic	12 W (48 Ω, with nominal voltage)
Nominal load, inductive	12 VA (1.2 H, 48 Ω, with nominal voltage)
Limitation of the voltage induced on circuit interruption	-28 V ... -17 V
Output voltage when switched off	max. 1 V
Output current when switched off	max. 20 µA
Signal delay	max. 150 µs (when switched on) max. 200 µs (when switched off)
Switching frequency	max. 5500 per second (with at least 50 mA load current) max. 1 per second (with inductive load)
Overload protection, short-circuit protection of outputs	yes
Behavior with overload	Auto restart
Reverse voltage resistance to short pulses	Reverse voltage proof
Overcurrent shut-down	min. 0.7 A

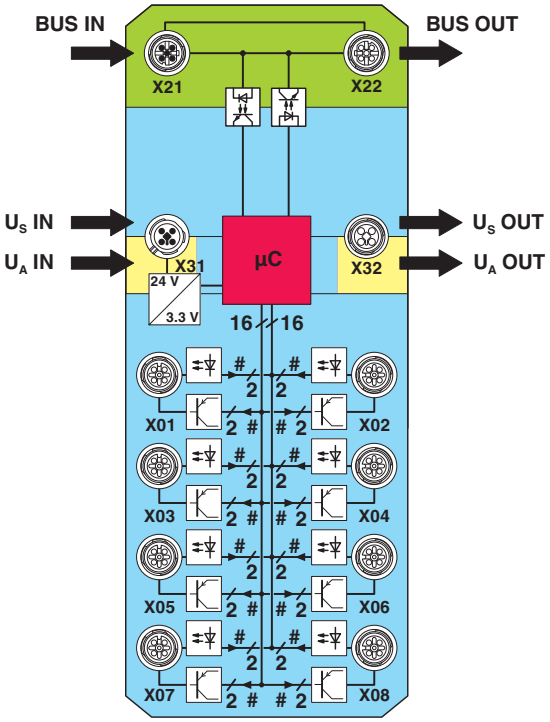
Configuration data	
ID number	0E59
Input address area	16 bit
Output address area	16 bit

Electrical isolation/isolation of the voltage areas	
Test section	**Test voltage**
24 V supply (communications power and sensor supply, digital inputs/outputs)/FE	500 V AC, 50 Hz, 1 min.
24 V supply (communications power/sensor supply, digital inputs/outputs)/FE	500 V AC, 50 Hz, 1 min.
Bus connection / FE	500 V AC, 50 Hz, 1 min.
24 V supply (actuator supply)/24 V supply (communications power and sensor supply, digital inputs/outputs)	500 V AC, 50 Hz, 1 min.
24 V supply (actuator supply)/bus connection	500 V AC, 50 Hz, 1 min.
24 V supply (actuator supply)/FE	500 V AC, 50 Hz, 1 min.

Mechanical tests	
Vibration resistance in accordance with EN 60068-2-6/IEC 60068-2-6	5g
Shock in accordance with EN 60068-2-27/IEC 60068-2-27	30g, 11 ms period, half-sine shock pulse
Continuous shock in accordance with EN 60068-2-27/IEC 60068-2-27	10g
Conformance with EMC Directive 2014/30/EU	
Immunity test in accordance with EN IEC 61000-6-2	
Electrostatic discharge (ESD) IEC 61000-4-2	Criterion B, ±6 kV contact discharge, ±8 kV air discharge
Electromagnetic fields IEC 61000-4-3	Criterion A, Field intensity: 10 V/m
Fast transients (burst) IEC 61000-4-4	Criterion B, ±2 kV
Transient overvoltage (surge) IEC 61000-4-5	Criterion B, DC supply lines: ±0.5 kV/±0.5 kV (symmetrical/asymmetrical)
Conducted interference IEC 61000-4-6	Criterion A, Test voltage 10 V
Noise emission test in accordance with EN IEC 61000-6-4	Class A
Approvals	
For the current approvals, go to:	www.phoenixcontact.com/product/2701499
Manufacturer's declarations	
For the current manufacturer’s declarations, go to:	www.phoenixcontact.com/product/2701499

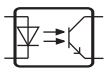
5 Internal circuit diagram

Figure 1 Internal wiring of connections



Key:

Green area:	Network
Blue area:	U_S
Yellow area:	U_A



Optocoupler



Power supply unit with electrical isolation



Microcontroller



Digital input



Digital output



LED



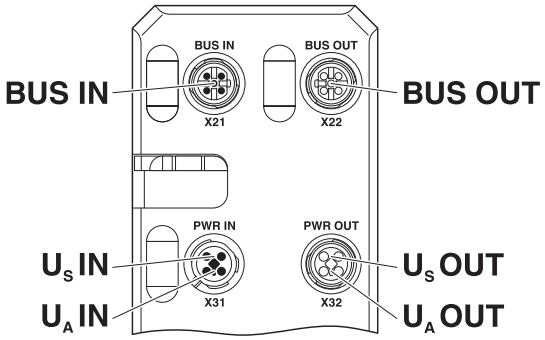
Transistor

The device and the freely configurable inputs and outputs are supplied from voltage U_S.
Voltage U_A is only routed through the device.
This means that the outputs cannot be switched off separately.

6 Pin assignment

6.1 PROFIBUS and power supply connection

Figure 2 Connections for PROFIBUS and power supply



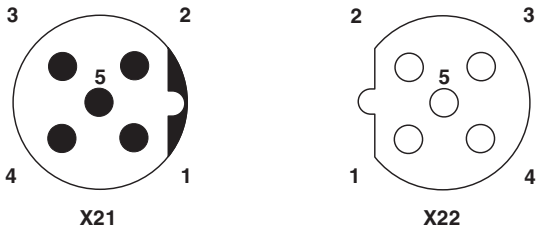
Designation	Meaning
BUS IN (X21)	PROFIBUS IN
BUS OUT (X22)	PROFIBUS OUT
U_S IN (X31)	Power supply IN (logic, sensors and actuators)
U_A IN (X31)	Power Supply IN (actuators) for additional devices
U_S OUT (X32)	Power supply OUT for additional devices
U_A OUT (X32)	Power supply OUT for additional devices

Ground the device by means of the mounting screws.

6.2 PROFIBUS pin assignment

The bus is connected via two B-coded M12 plug-in plugs. The incoming bus (IN) is a plug and the outgoing bus (OUT) is a socket.

Figure 3 PROFIBUS pin assignment, B-coded



Pin	Signal	Specification	Description
1	VP	V	5 V termination resistor
2	RxD / TxD-N (A)	A, RS-485, PD	Inverted bus cable
3	DGND	V	0 V
4	RxD / TxD-P (B)	B, RS-485, PU	Non-inverted bus cable
5	Not used	-	-

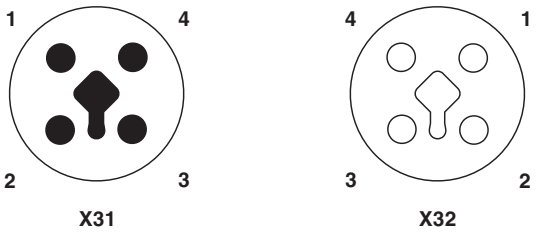
A	=	A line
B	=	B cable
RS-485	=	RS-485 level, bidirectional
V	=	Power supply
PU	=	Pullup
PD	=	Pulldown

The shield is connected to functional ground in the device.

The thread is used for additional shielding.

6.3 Pin assignment of the power supply U_S/U_A

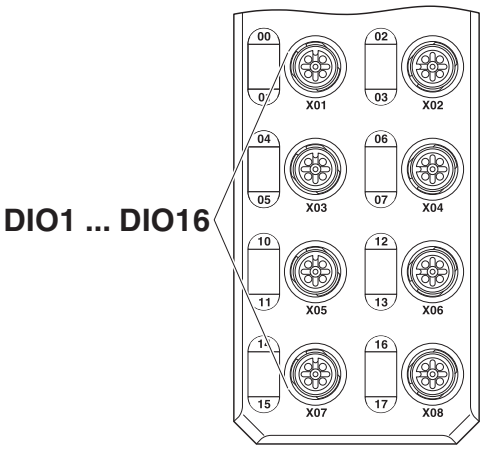
Figure 4 Pin assignment of the power supply, T-coded



Pin	IN	OUT	Conductor colors
1	+24 V DC (U_S)	+24 V DC (U_S)	Brown
2	GND (U_A)	GND (U_A)	White
3	GND (U_S)	GND (U_S)	Blue
4	+24 V DC (U_A)	+24 V DC (U_A)	Black

6.4 Connecting inputs and outputs

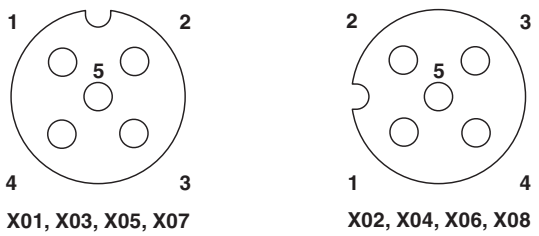
Figure 5 Input and output connections



Designation	Meaning
DIO1 ... DIO16 (X01 ... X08)	Inputs/outputs 1 ... 16

6.5 Pin assignment of the inputs and outputs

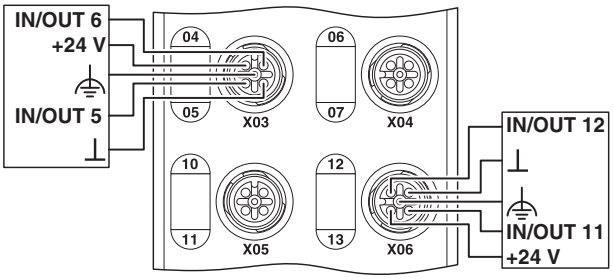
Figure 6 Pin assignment of the inputs and outputs, A-coded



Pin	Input/output socket
1	+24 V DC (U_S)
2	Input/output 2, 4, 6, ... 16
3	GND
4	Input/output 1, 3, 5, ... 15
5	FE

7 Connection example

Figure 7 Example of connection of sensors and actuators



8 Connection notes

NOTE: Data corruption or loss

Implement the FE connection using mounting screws, in order to ensure immunity to interference.

NOTE: device damage

In order to guarantee IP65/IP67 degree of protection, fit unused sockets with protective caps.

NOTE: Damage to the electronics

Only supply the sensors with the voltage U_S provided at the terminal points.

NOTE: Damage to the electronics

Observe the correct polarity of the supply voltages U_S and U_A in order to prevent damage to the device.

NOTE: Malfunction

When connecting the sensors and actuators, observe the assignment of the connections to the PROFIBUS input and output data.

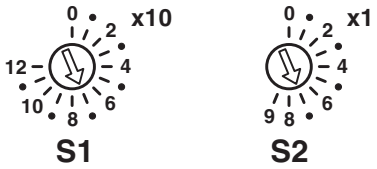
Secure the device to a level surface or to a profile. Do not use this device to bridge gaps, in order to prevent forces being transmitted via the device.

Use standard M5 screws with toothed lock washer and self-locking nuts. Observe the maximum torque of the screws.

9 Configuration via rotary encoding switch

Addresses are set using two rotary coding switches. Switch x10 is used to set the position in tens (x10) and switch x1 is used to set the position in units (x1). The address can be set between 1 and 126.

Figure 8 PROFIBUS rotary encoding switch



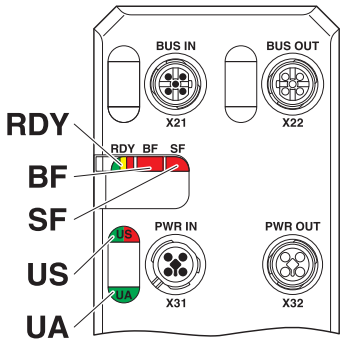
S1	S2	Code	Function
0	0	00	Reserved
0 ... 12	1 ... 5	01 ... 125	Manual address assignment
12	6	126	Setting the slave address (set slave address command)
12	7	127	Reserved
12	8	128	Reserved
12	9	129	Reserved

A new address value is only applied on device power up.

10 Local status and diagnostic indicators

10.1 Indicators for bus and power supply

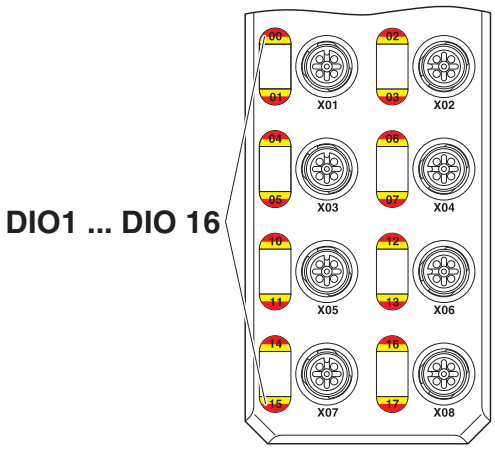
Figure 9 LEDs for bus and power supply



Designation	Color	Meaning	State	Description
RDY	Green/ yellow/ red	Ready	Green on	Device ready to operate
			Flashing yellow	Firmware update is being performed.
			Flashing green/ yellow	Over- or undervoltage at U_S
				Temperature of the device is in the critical area.
				And red US LED: sensor supply overload
			Red on	Rotary encoding switches are set to an invalid/reserved position.
			Off	Device is not ready for operation.
BF	Red	**B**us **F**ault	Red on	No communication on PROFIBUS
				Device is starting up.
				No baud rate detected by device.
			Red flashing	Device has not been configured by the master.
			Red flashing	Device configuration does not match.
				Invalid parameter data received from the master.
				Invalid bus address
				The device is in the clear or stop state. The outputs are in the safe state.
			Off	No error
SF	Red	Group error	Red on	Device-specific diagnostics present, e.g., short circuit at the I/O devices.
				Hardware is faulty.
				Device data or parameter data do not match.
			Off	No error
US	Green/ red	**U_S**ensors	Green on	Logic/sensor supply is sufficient.
			Off	Logic/sensor supply not available or insufficient.
			Red on	Sensor voltage overload
UA	Green	**U_A**ctuators	On	Actuator supply available.
			Off	Actuator supply not available.

10.2 Input and output indicators

Figure 10 Input and output indicators



Designation	Color	Meaning	State	Description
00 ... 07, 10 ... 17	Yellow	Status of the inputs and outputs when used as an input	On	Input is set.
			Off	Input is not set.
00 ... 07, 10 ... 17	Yellow/red	Status of the inputs and outputs when used as an output	Yellow on	Output is set.
			Red on	Output is short circuited or overloaded.
			Off	Output is not set.

The numbering of the LEDs is as follows: the first number specifies the byte, the second number specifies the bit.

11 Process data

11.1 Assignment of the terminal points to the IN process data

The I/O data are mapped as follows:

Input process data																
Byte	0								1							
Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
IN	07	06	05	04	03	02	01	00	17	16	15	14	13	12	11	10
Connection	X04		X03		X02		X01		X08		X07		X06		X05	
Pin	2	4	2	4	2	4	2	4	2	4	2	4	2	4	2	4
DI	8	7	6	5	4	3	2	1	16	15	14	13	12	11	10	9

Key:

Bit:	Process data assignment
IN:	LED marking
DI:	Device input

11.2 Assignment of the terminal points to the OUT process data

The I/O data are mapped as follows:

Output process data																
Byte	0								1							
Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
OUT	07	06	05	04	03	02	01	00	17	16	15	14	13	12	11	10
Connection	X04		X03		X02		X01		X08		X07		X06		X05	
Pin	2	4	2	4	2	4	2	4	2	4	2	4	2	4	2	4
DO	8	7	6	5	4	3	2	1	16	15	14	13	12	11	10	9

Key:

Bit:	Process data assignment
OUT:	LED marking
DO:	Device output

11.3 Status module

The device has a status module in slot 1. The status is mapped as follows.

Bit 31 ... bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Supply of the module electronics, sensors, and actuators (U_S)		Reserved		Outputs	
	Undervoltage	Overload			Reserved	Overload/ short circuit

11.4 Configuration of digital inputs and outputs

A channel, whether an input or an output, is configured by using the IN or OUT process data according to the channel function. Parameterization is not necessary.

If you use the channel as an output, the status of the channel is also mapped in the input process data. This can be useful for diagnostic purposes, for example.
If you use the channel as an input, you cannot use the channel simultaneously as an output.

12 Parameterization

This section provides a detailed description of the format of the parameters for the input and output devices.

This may be useful when setting parameters using acyclic services or if there is no user interface for the simple selection of parameters.

Byte	Meaning
1 ... 7	DP standard
8 ... 10	DP/V1 standard
11 ... 13	Module parameter

Module parameter			
Byte	**Meaning**	**Contents**	
11	Behavior of the device	Bit 0 and Bit 1	Substitute value behavior
			00_{bin}: “0” is output to all output bits
			01_{bin}: “1” is output to all output bits
			10_{bin}: hold last value
			11_{bin}: substitute value
		Other	Reserved
12	Substitute values of individual channels 1 ... 8	Bit 0	Substitute value for channel 1 (X01.00)
		Bit 1	Substitute value for channel 2 (X01.01)
		Bit 2	Substitute value for channel 3 (X02.02)
		Bit 3	Substitute value for channel 4 (X02.03)
		Bit 4	Substitute value for channel 5 (X03.04)
		Bit 5	Substitute value for channel 6 (X03.05)
		Bit 6	Substitute value for channel 7 (X04.06)
		Bit 7	Substitute value for channel 8 (X04.07)
13	Substitute value behavior of individual channels 9 ... 16	Bit 0	Substitute value for channel 9 (X05.10)
		Bit 1	Substitute value for channel 10 (X05.11)
		Bit 2	Substitute value for channel 11 (X06.12)
		Bit 3	Substitute value for channel 12 (X06.13)
		Bit 4	Substitute value for channel 13 (X07.14)
		Bit 5	Substitute value for channel 14 (X07.15)
		Bit 6	Substitute value for channel 15 (X08.16)
		Bit 7	Substitute value for channel 16 (X08.17)

13 I&M functions

The following Information & Maintenance functions are supported:

I&M 0

I&M data	Access / data type	Presets
MANUFACTURER_ID	Read / 2 bytes	$B0_{hex}$ (PHOENIX CONTACT GmbH & Co. KG)
ORDER_ID	Read / 20 bytes	-
SERIAL_Number	Read / 16 bytes	-
HARDWARE_Revision	Read / 2 bytes	-
SOFTWARE_Revision	Read / 4 bytes	-
REVISION_Counter	Read / 2 bytes	0000_{hex} (reserved)
PROFILE_ID	Read / 2 bytes	$F600_{hex}$ (generic device)
PROFILE_SPECIFIC_TYPE	Read / 2 bytes	0003_{hex} (I/O modules)
IM_VERSION	Read / 2 bytes	0102_{hex} (Version 1.2)
IM_SUPPORTED	Read / 2 bytes	$000E_{hex}$ (I&M 1 ... 3)

I&M 1

I&M data	Access / data type	Presets
TAG_FUNCTION	Read/write / 32 bytes	“20_{hex}” (empty)
TAG_LOCATION	Read/write / 22 bytes	“20_{hex}” (empty)

I&M 2

I&M data	Access / data type	Presets
INSTALLATION_DATE	Read/write / 16 bytes	“20_{hex}” (empty)
RESERVED	Read/write / 38 bytes	00_{hex}

I&M 3

I&M data	Access / data type	Presets
DESCRIPTOR	Read/write / 54 bytes	“20_{hex}” (empty)

14 Sync/freeze mode

The device supports sync and freeze mode.

The functions must be activated by the PROFIBUS master in the parameter data.

Input and output data is written or read at defined times with the sync and freeze commands.

If the device receives a sync command from the PROFIBUS master at any given time, the current OUT process data is transferred and frozen until the next sync command.

Similarly, the states of the inputs are transferred on the respective freeze command and are frozen until the next freeze command.

15 Diagnostic alarms

PROFIBUS enables the PROFIBUS device to store diagnostic information together with the error location and error type.

The alarms are enabled in the delivery state. However, you can disable the alarms on startup via parameters.

An incoming alarm informs the PROFIBUS device that diagnostic information has been entered.

When the diagnostic information has been removed, an outgoing alarm is sent to the device.

If at least one piece of diagnostic information is stored, the SF LED is on. If no diagnostic information is present, the SF LED is off.

The following PROFIBUS diagnostic messages are indicated by the PROFIBUS device:

Diagnostic messages	Process data status bit	Network-specific diagnostic image
Device overtemperature	-	yes
Undervoltage U_S	Bit 5	yes
Overload U_S	Bit 4	yes
Overvoltage U_S	-	yes
Overload/short circuit of an output	Bit 0	yes

Channel diagnostics are always reported in groups of 4. The LED status can be found in the section “Local status and diagnostics indicators”.

16 Monitoring

A process data watchdog is integrated into the device to avoid uncontrolled setting/resetting of outputs in the event of an error.

If device outputs are set, the controlling process must be able to access the device.

In the event of an error, e.g., bus cable interrupted or function error in the controlling process, the device can respond appropriately via the process data watchdog.

When you activate the process data watchdog, it is started by the first write process. It expects the next write process within the timeout period. In error-free operation, the write process is performed during the timeout period. The watchdog is then restarted (triggered).

Reading calls do not trigger the process data watchdog.

If there is no triggering during the timeout period, an error has occurred. Two responses follow:

– All outputs are set to the configured substitute value.
– The BF LED indicates the corresponding state.

17 Substitute value behavior

If PROFIBUS communication fails or if no valid process data is received from the PROFIBUS master, all device outputs are set to the parameterized substitute values.